

Existence and stability results for a system of hybrid fractional differential problems

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Abstract

In this paper, we are concerned with a system of hybrid fractional differential equations. We begin by establishing the existence and uniqueness results using the Banach contraction principle. Then, we derive sufficient conditions for proving an existence results by using of Leray-Schauder fixed point theorem. Also, we discuss the Ulam-Hyres stability for the mentioned hybrid system. At the end, we present an example to illustrate one of our main results.

Subject Classification (2010): 34A38, 32A65, 26A33.

Keywords: *Caputo fractional derivative, Fixed point, Existence, Hybrid differential equations, Ulam-Hyres stability.*

1. Introduction

Differential problems with fractional calculus arise in many scientific disciplines, see [10, 13, 14, 15, 26]. By applying some fractional derivative operators, many authors have established uniqueness and existence results for some types of problems with arbitrary order, for instance see [5, 12, 23, 24, 25, 30]. Several scholars have studied the existence, uniqueness, of solutions of

This article has been corrected with minor changes. These changes do not impact the academic content of the article.

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fractional systems. For more details, one can consult [1, 4, 8, 20, 21, 22] and the references cited therein. Also, fractional hybrid differential problems have been studied by many researchers, see for instance [6, 7, 9, 17, 18, 31]. Recently, some scholars have discussed the stability of solutions of hybrid differential equations involving fractional calculus [2, 3, 16, 27] and the references cited therein. The standard form of hybrid differential problem [11] is given by the following differential equation

$$\begin{cases} D^1 \left[\frac{q(\tau)}{f(\tau, q(\tau))} \right] = h(\tau, q(\tau)), \tau \in \Delta, \\ q(\tau_0) = q_0, q_0 \in \mathbb{R}, \end{cases}$$

where $\Delta = [0, T]$, $f \in C(\Delta \times \mathbb{R}, \mathbb{R} - \{0\})$ and $h \in C(\Delta \times \mathbb{R}, \mathbb{R})$. Several scholars have studied fractional types of the above hybrid differential equation. For example in [31], the authors considered a the hybrid fractional differential equations with Riemann-Liouville differential operators

$$\begin{cases} D^\alpha \left[\frac{q(\tau)}{f(\tau, q(\tau))} \right] = h(\tau, q(\tau)), \tau \in \Delta, 0 < \alpha < 1, \\ q(0) = 0, \end{cases}$$

where $f: \Delta \times \mathbb{R} \rightarrow \mathbb{R} - \{0\}$ and $h: \Delta \times \mathbb{R} \Rightarrow \mathbb{R}$. In [19], the authors considered a fractional coupled hybrid problems of the forme

$$\begin{cases} D^{\alpha_1} \left[\frac{q(\tau)}{f_1(\tau, q(\tau), p(\tau))} \right] = h_1(\tau, q(\tau), p(\tau)), \\ D^{\alpha_2} \left[\frac{p(\tau)}{f_2(\tau, q(\tau), p(\tau))} \right] = h_2(\tau, q(\tau), p(\tau)), \\ q(0) = q(1) = 0, p(0) = p(1) = 0, \\ t \in \Phi := [0, 1], 1 < \alpha_1, \alpha_2 \leq 2, \end{cases}$$

where $f_1, f_2: \Phi \times \mathbb{R} \rightarrow \mathbb{R} - \{0\}$ and $h_1, h_2: \Phi \times \mathbb{R} \rightarrow \mathbb{R}$. In the current work, we study the existence, uniqueness and stability of solutions for the following system:

$$\begin{cases} D^{\alpha_1} \left(\frac{q_1(\tau)}{f_1(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau))} \right) = h_1(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau)), \\ D^{\alpha_2} \left(\frac{q_2(\tau)}{f_2(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau))} \right) = h_2(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau)), \\ \vdots \\ D^{\alpha_k} \left(\frac{q_k(\tau)}{f_k(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau))} \right) = h_k(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau)), \\ q_i(0) = \theta_i \int_0^{\beta_i} \varphi_i(r) q_i(r) dr, \\ t \in \Phi, 0 < \alpha_i < 1, 0 < \beta_i < 1, \theta_i \in \mathbb{R}, i \in \{1, 2, \dots, k\}, \end{cases}$$

where, D^{α_i} is the derivative in the sense of Caputo, $\varphi_i \in C([0, \beta_i])$, $f_i: \Phi \times \mathbb{R}^k \rightarrow \mathbb{R} - \{0\}$ and $h_i: \Phi \times \mathbb{R}^k \rightarrow \mathbb{R}, i \in \{1, 2, \dots, k\}$.

We describe some basic notations of fractional integrals and derivatives in this section 2. Section 3 is devoted to discuss the uniqueness result for (1) using the Banach contraction principle. We also prove an existence result by means of Leray Schauder alternative in this section. In Section 4, we present the Hyers-Ulam stability of system. In last section, an example is given.

2. Preliminaries

We present some useful definitions and lemmas [28, 29]. As notation, we put: $\bar{q} = (q_1, q_2, \dots, q_k)$ and $\bar{q}(\tau) = (q_1(\tau), q_2(\tau), \dots, q_k(\tau))$. We have:

Definition 1: The Riemann-Liouville fractional integral operator of order $\vartheta \geq 0$, for $\psi \in C([a, b])$ is defined as:

$$I^\vartheta[\psi(\tau)] = \frac{1}{\Gamma(\vartheta)} \int_a^\tau (\tau - s)^{\vartheta-1} \psi(s) ds, \vartheta > 0,$$

$$I^0[\psi(\tau)] = \psi(\tau),$$

where $\Gamma(\vartheta) := \int_0^\infty e^{-u} u^{\vartheta-1} du$.

Definition 2: Let $\psi \in C^n([a, b]), n-1 < \vartheta < n, n \in \mathbb{N}^*$. The Caputo fractional derivative for ψ is given by:

$$D^\vartheta[\psi(\tau)] = \frac{1}{\Gamma(n-\vartheta)} \int_a^\tau (\tau - s)^{n-\vartheta-1} \psi^{(n)}(s) ds.$$

Furthermore, we recall the following lemmas [25]:

Lemma 3: Suppose that $\vartheta > 0$ and $n-1 < \vartheta < n, n \in \mathbb{N}^*$. Thus, general solution of $D^\vartheta x(t) = 0$ is given by

$$w(\tau) = e_0 + e_1\tau + e_2\tau^2 + \dots + e_{n-1}\tau^{n-1},$$

such that $e_i \in \mathbb{R}, i = \overline{0, n-1}$.

Lemma 4: Let $\vartheta > 0$. Then

$$I^\vartheta [D^\vartheta[w(\tau)]] = w(\tau) + e_0 + e_1\tau + e_2\tau^2 + \dots + e_{n-1}\tau^{n-1},$$

for some $e_i \in \mathbb{R}, i = \overline{0, n-1}$.

Lemma 5: For $i = 1, \dots, k$, let $f_i \in C(\Phi \times \mathbb{R}^k, \mathbb{R} - \{0\})$ and $g_i \in C(\Phi, \mathbb{R})$. Then, the solution of the problem

$$D^{\alpha_i} \left(\frac{q_i(\tau)}{f_i(\tau, \bar{q}(\tau))} \right) = g_i(\tau), \tau \in \Phi, 0 < \alpha_i < 1, \quad (2)$$

with

$$q_i(0) = \theta_i \int_0^{\beta_i} \varphi_i(s) q_i(s) ds, 0 < \beta_i < 1, i = 1, 2, \dots, k, \quad (3)$$

with $\theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \varphi_i(r) dr \neq f_i(0, \bar{q}(0))$, is given by $\bar{q}(\tau)$, such that

$$\begin{aligned}
q_i(t) &= f_i(t, \bar{q}(\tau)) \times \left(\frac{1}{\Gamma(\alpha_i)} \int_0^\tau (\tau - s)^{\alpha_i-1} g_i(s) ds \right. \\
&\quad \left. + \frac{\theta_i}{[f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \varphi_i(r) dr]} \right. \\
&\quad \left. \times \int_0^{\beta_i} f_i(r, \bar{q}(r)) \varphi_i(r) \left[\frac{1}{\Gamma(\alpha_i)} \int_0^r (r - \tau)^{\alpha_i-1} g_i(\tau) d\tau \right] dr \right). \tag{4}
\end{aligned}$$

Proof: Let q_i $i \in \{1, 2, \dots, k\}$ be a solution for the system. By using Lemma 4, we have

$$\frac{q_i(\tau)}{f_i(\tau, \bar{q}(\tau))} = I^{\alpha_i} g_i(\tau) + e_0, \tag{5}$$

where $e_0 \in \mathbb{R}$.

Alternatively, we have

$$q_i(\tau) = f_i(\tau, \bar{q}(\tau)) (I^{\alpha_i} [g_i(\tau)] + e_0), \tau \in \Lambda, i = 1, 2, \dots, k. \tag{6}$$

Multiplying (6) by $\theta_i \varphi_i(r)$, we can write

$$\theta_i \varphi_i(r) x_i(r) = \theta_i f_i(r, q(r)) \varphi_i(r) I^{\alpha_i} [g_i(r)] + e_0 \theta_i f_i(r, q(r)) \varphi_i(r). \tag{7}$$

Integrating (7) with respect to r over $(0, \beta_i)$, yields

$$\begin{aligned}
&\theta_i \int_0^{\beta_i} \varphi_i(r) q_i(r) dr \\
&= \theta_i \int_0^{\beta_i} f_i(r, q(r)) \varphi_i(r) I^{\alpha_i} [g_i(r)] dr + e_0 \theta_i \int_0^{\beta_i} f_i(r, q(r)) \varphi_i(r) dr.
\end{aligned} \tag{8}$$

Using (3) and (5), we can obtain

$$\begin{aligned}
&c_0 \left(f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \varphi_i(r) dr \right) \\
&= \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \varphi_i(r) I^{\alpha_i} [g_i(r)] dr.
\end{aligned} \tag{9}$$

This implies that

$$\begin{aligned}
c_0 &= \frac{\theta_i}{(f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \varphi_i(r) dr)} \\
&\quad \times \int_0^{\beta_i} f_i(r, \bar{q}(r)) \varphi_i(r) I^{\alpha_i} [g_i(r)] dr.
\end{aligned} \tag{10}$$

Taking into account the value of e_0 (6), we obtain (4).

3. Existence and uniqueness results

For $i \in \{1, 2, \dots, k\}$, we introduce the spaces

$$W_i = \{q_i(t), i = 1, 2, \dots, k; q_i \in C(\Phi, R)\}$$

endowed the norm defined by

$$\|q_i\|_{W_i} = \sup\{|q_i(t)| : t \in \Phi\}.$$

It is clear that for each $i \in \{1, 2, \dots, k\}$, $(W_i, \|\cdot\|_{W_i})$ is a Banach space. The product space $\left(\prod_{i=1}^k W_i, \|\cdot\|_{\prod_{i=1}^k W_i}\right)$ is also a Banach space with norm $\|\bar{q}\|_{\prod_{i=1}^k W_i} = \|q_1\|_{W_1} + \|q_2\|_{W_2} + \dots + \|q_k\|_{W_k}$.

Now, we define $\Phi: \prod_{i=1}^k W_i \rightarrow \prod_{i=1}^k W_i$ by:

$$\phi \bar{q}(\tau) = (\phi_1 \bar{q}(\tau), \phi_2 \bar{q}(\tau), \dots, \phi_k \bar{q}(\tau)),$$

where,

$$\begin{aligned} \phi_i \bar{q}(\tau) &= f_i(\tau, \bar{q}(\tau)) \times \left(\frac{1}{\Gamma(\alpha_i)} \int_0^\tau (\tau - s)^{\alpha_i-1} h_i(s, \bar{q}(s)) ds \right. \\ &\quad \left. + \frac{\theta_i}{[f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \phi_i(r) dr]} \right. \\ &\quad \left. \times \int_0^{\beta_i} f_i(r, \bar{q}(r)) \phi_i(r) \left[\frac{1}{\Gamma(\alpha_i)} \int_0^r (r - s)^{\alpha_i-1} h_i(s, \bar{q}(s)) ds \right] dr \right), \end{aligned} \quad (11)$$

for $i \in \{1, 2, \dots, k\}$.

Now, we consider the following conditions.

(A₁): There exist nonnegative constants $q_{ij}, i, j = 1, 2, \dots, k$, such that for all $\tau \in \Phi$ and $\bar{q}, \bar{p} \in \mathbb{R}^k$, we have

$$|h_i(\tau, \bar{q}) - h_i(\tau, \bar{p})| \leq \sum_{j=1}^k \omega_{ij} |q_j - p_j|.$$

(A₂): $f_i: \Phi \times \mathbb{R}^k \rightarrow \mathbb{R} - \mathbb{R} - \{0\}$ are continuous and there exist constants $N_i > 0$ which $\tau \in \Lambda$ and $\bar{w} \in \mathbb{R}^k$, $|f_i(\tau, \bar{w})| \leq N_i, i \in \{1, 2, \dots, k\}$.

(A₃): Let for $\sigma_i > 0$ and $\delta_{ij} \geq 0$ ($i, j = 1, 2, \dots, k$) such that, $|h_i(\tau, \bar{w})| \leq \sigma_i + \sum_{j=1}^k \delta_{ij} |w_j|$ for all $\tau \in \Phi, \bar{w} \in \mathbb{R}^k$.

Then, we set the following quantities:

$$\Sigma_i = \frac{N_i}{\Gamma(\alpha_i+1)} + \frac{N_i \beta_i^{\alpha_i+1} |\theta_i| \sup_{s \in J} |\phi_i(r)|}{[f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(s, \bar{q}(s)) \phi_i(r) dr] \Gamma(\alpha_i+2)}, \quad (12)$$

where $i \in \{1, 2, \dots, k\}$.

Theorem 6: Let $h_i: \Phi \times \mathbb{R}^k \rightarrow \mathbb{R}, i \in \{1, 2, \dots, k\}$ be continuous functions satisfying the hypotheses (A₁) and (A₂).

If

$$\sum_{i=1}^k (\Lambda_i \sum_{j=1}^k \omega_{ij}) < 1, \quad (13)$$

then, (1) admits only one solution on Φ .

Proof: Put $L_i = \sup_{\tau \in \Phi} |h_i(\tau, 0, 0, \dots, 0)| < \infty, i = 1, 2, \dots, k$ and then define r , such that

$$\mu \geq \frac{\sum_{i=1}^k \Lambda_i L_i}{1 - \sum_{i=1}^k \Lambda_i \sum_{j=1}^k \omega_{ij}}.$$

We first show that $\phi B_\mu \subset B_\mu$, where $B_\mu = \{\bar{q} \in \prod_{i=1}^k W_i: \|\bar{q}\|_{\prod_{i=1}^k W_i} \leq \mu\}$. So thanks to (A₁), for $\bar{q} \in B_\mu$, we observe that

$$\begin{aligned} |h_i(\tau, \bar{q}(\tau))| &\leq |h_i(\tau, \bar{q}(\tau)) - h_i(\tau, 0, 0, \dots, 0)| + |h_i(\tau, 0, 0, \dots, 0)| \\ &\leq \sum_{j=1}^k \omega_{ij} \mu + L_i. \end{aligned} \quad (14)$$

Hence, we get

$$\begin{aligned} \|\phi_i(\bar{q})\|_{W_i} &\leq N_i \times \sup_{\tau \in \Phi} \left\{ \left(\frac{1}{\Gamma(\alpha_i)} \int_0^\tau (\tau - s)^{\alpha_i-1} |h_i(s, \bar{q}(s))| ds \right. \right. \\ &\quad \left. \left. + \frac{|\theta_i|}{\left| f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \phi_i(r) dr \right|} \right. \right. \\ &\quad \left. \left. \times \int_0^{\beta_i} |\phi_i(r)| \left[\frac{1}{\Gamma(\alpha_i)} \int_0^r (r - s)^{\alpha_i-1} |h_i(s, \bar{q}(s))| ds \right] dr \right\}. \end{aligned} \quad (15)$$

Using (14), we obtain

$$\begin{aligned} &\|\phi_i(\bar{q})\|_{W_i} \\ &\leq \left[\frac{N_i}{\Gamma(\alpha_i+1)} + \frac{N_i \beta_i^{\alpha_i+1} |\theta_i| \sup_{r \in \Phi} |\phi_i(r)|}{\left| f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \phi_i(r) dr \right| \Gamma(\alpha_i+2)} \right] \\ &\quad \times (\sum_{j=1}^k \omega_{ij} \mu + L_i) \\ &= \Lambda_i (\sum_{j=1}^k \omega_{ij} \mu + L_i), i = 1, 2, \dots, k. \end{aligned} \quad (16)$$

This implies that

$$\|\phi_i(\bar{q})\|_{W_i} \leq \Lambda_i (\sum_{j=1}^k \omega_{ij} \mu + L_i), i = 1, 2, \dots, k. \quad (17)$$

Consequently,

$$\|\phi \bar{q}\|_{\Gamma_{i=1}^k W_i} \leq \mu, \quad (18)$$

which implies that $\phi B_\mu \subset B_\mu$.

Next, for $\bar{q}, \bar{p} \in W$ and, for all $\tau \in \Lambda$, we get

$$\begin{aligned} &\|\phi_i(\bar{q}) - \phi_i(\bar{p})\|_{W_i} \\ &\leq N_i \times \sup_{\tau \in \Phi} \left\{ \left(\frac{1}{\Gamma(\alpha_i)} \int_0^\tau (\tau - s)^{\alpha_i-1} |h_i(s, \bar{q}(s)) - h_i(s, \bar{p}(s))| ds \right. \right. \\ &\quad \left. \left. + \frac{|\theta_i|}{\left| f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \phi_i(r) dr \right|} \int_0^{\beta_i} |\phi_i(r)| \right. \right. \\ &\quad \left. \left. \times \left[\frac{1}{\Gamma(\alpha_i)} \int_0^r (r - s)^{\alpha_i-1} |h_i(s, \bar{q}(s)) - h_i(s, \bar{p}(s))| ds \right] dr \right\}. \end{aligned} \quad (19)$$

Thanks to (A_1) , we can write

$$\begin{aligned} &\|\phi_i(\bar{q}) - \phi_i(\bar{p})\|_{W_i} \\ &\leq \sum_{j=1}^k \omega_{ij} N_i \times \sup_{\tau \in \Phi} \left\{ \left(\frac{1}{\Gamma(\alpha_i)} \int_0^\tau (\tau - s)^{\alpha_i-1} \sum_{j=1}^k \|q_j - p_j\| ds \right. \right. \\ &\quad \left. \left. + \frac{|\theta_i|}{\left| f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \phi_i(r) dr \right|} \int_0^{\beta_i} |\phi_i(r)| \right. \right. \\ &\quad \left. \left. \times \left[\frac{1}{\Gamma(\alpha_i)} \int_0^r (r - s)^{\alpha_i-1} \sum_{j=1}^k \|q_j - p_j\| ds \right] dr \right\} \\ &\leq \sum_{j=1}^k \omega_{ij} \left[\frac{N_i}{\Gamma(\alpha_i+1)} \right. \\ &\quad \left. + \frac{N_i \beta_i^{\alpha_i+1} |\theta_i| \sup_{r \in \Phi} |\phi_i(r)|}{\left| f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \phi_i(r) dr \right| \Gamma(\alpha_i+2)} \right] (\sum_{j=1}^k \|q_j - p_j\|) \\ &= \sum_{j=1}^k \omega_{ij} \Lambda_i \times (\sum_{j=1}^k \|q_j - p_j\|), \end{aligned} \quad (20)$$

for $i = 1, 2, \dots, k$.

This implies that

$$\|\phi(\bar{q}) - \phi(\bar{p})\|_{\prod_{i=1}^k W_i} \leq \sum_{i=1}^k (\Lambda_i \sum_{j=1}^k \omega_{ij}) \times (\sum_{j=1}^k \|q_j - p_j\|). \quad (21)$$

Since $\sum_{i=1}^k (\Lambda_i \sum_{j=1}^k \omega_{ij}) < 1$, by the given assumption, therefore ϕ is a contractive. Hence it follows, by Banach's fixed point theorem ϕ has a unique fixed point, which is a solution of system (1).

The following existence result for system (1) is based on Lemma of [15].

Theorem 7: Let $h_i: \Lambda \times \mathbb{R}^k \rightarrow \mathbb{R}, i = 1, 2, \dots, k$ be continuous functions satisfying the hypotheses (A_2) and (A_3) and also

$$\sum_{i=1}^k (\Lambda_i \sum_{j=1}^k \delta_{ij}) < 1,$$

then (1) admits one solution at least defined on Φ .

Proof: We begin by showing that ϕ is completely continuous. The application ϕ is continuous.

Let $\Omega \subset \prod_{i=1}^k W_i$ be bounded. Then we can find M_i ($M_i > 0$), such that

$$|h_i(\tau, \bar{q}(\tau))| \leq M_i, \forall \bar{q} \in \Omega.$$

Then for any $\bar{q} \in \Omega$ and for $i = 1, 2, \dots, k$, we have

$$\begin{aligned} \|\phi_i \bar{q}\|_{W_i} &\leq N_i \times \left(\frac{1}{\Gamma(\alpha_i)} \int_0^\tau (\tau - s)^{\alpha_i-1} |h_i(s, \bar{q}(s))| ds \right. \\ &\quad \left. + \frac{|\theta_i|}{|f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \varphi_i(r) dr|} \right. \\ &\quad \left. \times \int_0^{\beta_i} |\varphi_i(r)| \left[\frac{1}{\Gamma(\alpha_i)} \int_0^r (r - s)^{\alpha_i-1} |h_i(s, \bar{q}(s))| ds \right] dr \right), \end{aligned} \quad (22)$$

Hence, for all $i = 1, 2, \dots, k$, we obtain

$$\begin{aligned} &\|\phi_i \bar{q}\|_{W_i} \\ &\leq M_i \times \left[\frac{N_i}{\Gamma(\alpha_i+1)} + \frac{N_i |\theta_i| \beta_i^{\alpha_i+1} \sup_{r \in \Phi} |\varphi_i(r)|}{|f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \varphi_i(r) dr| \Gamma(\alpha_i+2)} \right] \\ &:= M_i \Lambda_i, \end{aligned} \quad (23)$$

and so

$$\|\phi \bar{q}\|_{\prod_{i=1}^k W_i} \leq \sum_{i=1}^k M_i \Lambda_i := M. \quad (24)$$

Thus, it follows from (24), that $\|\phi \bar{q}\|_{\prod_{i=1}^k W_i} < \infty$.

Next, we demonstrate that ϕ is equicontinuous. Let $\tau_1, \tau_2 \in Y$ with $\tau_1 < \tau_2$. Then

$$\begin{aligned} |\phi_i \bar{q}(\tau_2) - \phi_i \bar{q}(\tau_1)| &\leq \frac{N_i}{\Gamma(\alpha_i)} \int_0^{\tau_1} |(\tau_2 - s)^{\alpha_i-1} - (\tau_1 - s)^{\alpha_i-1}| |h_i(s, \bar{q}(s))| ds \\ &\quad + \frac{N_i}{\Gamma(\alpha_i)} \int_{\tau_1}^{\tau_2} |(\tau_2 - s)^{\alpha_i-1}| |h_i(s, \bar{q}(s))| ds. \end{aligned} \quad (25)$$

for $i = 1, 2, \dots, k$. Hence, we have

$$|\phi_i \bar{q}(\tau_2) - \phi_i \bar{q}(\tau_1)| \leq \frac{N_i M_i}{\Gamma(\alpha_i+1)} [(\tau_2 - \tau_1)^{\alpha_i} + |\tau_2^{\alpha_i} - \tau_1^{\alpha_i}|], i = 1, 2, \dots, k. \quad (26)$$

Thus,

$$\|\phi \bar{q}(\tau_2) - \phi \bar{q}(\tau_1)\|_{\prod_{i=1}^k W_i} \leq \sum_{i=1}^k \frac{N_i M_i}{\Gamma(\alpha_i+1)} [(\tau_2 - \tau_1)^{\alpha_i} + |\tau_2^{\alpha_i} - \tau_1^{\alpha_i}|]. \quad (27)$$

The right hand side of (27) tend to zero independently of $\bar{q}$ as $\tau_2 \rightarrow \tau_1$. Therefore, the operator ϕ is completely continuous.

Finally, we show the set $Y = \{\bar{q} \in \prod_{i=1}^k W_i, \bar{q} = \lambda \phi \bar{q}, 0 < \lambda < 1\}$ is bounded. Let $\bar{x} \in Y$. Then, for each $\tau \in \Phi$, we have

$$q_i(t) = \lambda \phi_i \bar{q}, i = 1, 2, \dots, k. \quad (28)$$

Then, for $i = 1, 2, \dots, k$, we obtain

$$\begin{aligned} |q_i(t)| &\leq \lambda N_i \times \left(\frac{1}{\Gamma(\alpha_i)} \int_0^\tau (\tau - s)^{\alpha_i-1} |h_i(s, \bar{q}(s))| ds \right. \\ &\quad + \frac{|\theta_i|}{|f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(r)) \phi_i(r) dr|} \\ &\quad \times \left. \int_0^{\beta_i} |\phi_i(r)| \left[\frac{1}{\Gamma(\alpha_i)} \int_0^r (r - s)^{\alpha_i-1} |h_i(s, \bar{q}(s))| ds \right] dr \right). \end{aligned} \quad (29)$$

Thanks to (A_3) , we can write

$$\begin{aligned} |q_i(t)| &\leq N_i \times \left(\frac{1}{\Gamma(\alpha_i+1)} + \frac{|\theta_i| \beta_i^{\alpha_i+1} \sup_{r \in \Phi} |\phi_i(r)|}{|f_i(0, \bar{q}(0)) - \theta_i \int_0^{\beta_i} f_i(r, \bar{q}(s)) \phi_i(r) dr| \Gamma(\alpha_i+2)} \right) \\ &\quad \times (\sigma_i + \sum_{j=1}^k \delta_{ij} \|q_j\|). \end{aligned} \quad (30)$$

Hence, we have

$$\|q_i\|_{W_i} \leq \Lambda_i \sigma_i + \Lambda_i \sum_{j=1}^k \delta_{ij} \|q_j\|, i = 1, 2, \dots, k. \quad (31)$$

This implies that

$$\sum_{i=1}^k \|q_i\|_{W_i} \leq \sum_{i=1}^k \Lambda_i \sigma_i + \sum_{i=1}^k \Lambda_i \sum_{j=1}^k \delta_{ij} \|q_j\|, \quad (32)$$

and so

$$\|\bar{q}\|_{\prod_{i=1}^k W_i} \leq \frac{\sum_{i=1}^k \Lambda_i \sigma_i}{\Pi}, \quad (33)$$

where $\Pi = \min_{1 \leq j \leq n} \left(1 - \sum_{i=1}^k (\Lambda_i \sum_{j=1}^k \delta_{ij}) \right)$. This shows that Y is bounded. Consequently, system (1) admits a solution.

4. Stability results

In this part, we will define and study the Ulam-Hyers stability (UH-stability) of the fractional hybrid system (1). For $\tau \in \Phi$, we have:

$$\begin{cases} \left| D^{\alpha_1} \left(\frac{q_1(\tau)}{f_1(\tau, w_1(\tau), w_2(\tau), \dots, w_k(\tau))} \right) - h_1(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau)) \right| \leq v_1, \\ \left| D^{\alpha_2} \left(\frac{q_2(\tau)}{f_2(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau))} \right) - h_2(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau)) \right| \leq v_2, \\ \vdots \\ \left| D^{\alpha_k} \left(\frac{q_k(\tau)}{f_k(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau))} \right) - h_k(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau)) \right| \leq v_k, \end{cases} \quad (34)$$

where $v_i, i = 1, 2, \dots, k$, are positive real numbers.

Definition 8: Fractional hybrid system (1) is UH-stable if $\forall v > 0$ which $v = \max\{v_i, i = 1, 2, \dots, k\} > 0$ and for each solution $\bar{p} \in \prod_{i=1}^k W_i$ of (34), there exists a solution $\bar{q} \in \prod_{i=1}^k W_i$ of the system (1) and $\exists \eta_{f_i, h_i} > 0$ with

$$\|\bar{p} - \bar{q}\|_{\prod_{i=1}^k W_i} \leq \eta_{f_i, h_i} v, i = 1, 2, \dots, k.$$

Definition 9: Fractional hybrid system (1) is generalized UH-stable if there exists $\psi_{f_i, h_i} \in C(\mathbb{R}_+, \mathbb{R}_+)$, $\psi_{f_i, h_i}(0) = 0, i = 1, 2, \dots, k$ such that for each solution $\bar{p} \in \prod_{i=1}^k W_i$ of (34) there exists a solution $\bar{q} \in \prod_{i=1}^k W_i$ of the system (1) with

$$\|\bar{p} - \bar{q}\|_{\prod_{i=1}^k X_i} \leq \psi_{f_i, h_i}(v), i = 1, 2, \dots, k.$$

Theorem 10: Assume that hypotheses $(A_j), j = 1, 2$ hold. If

$$\sum_{i=1}^k \frac{N_i}{\Gamma(\alpha_i + 1)} < \frac{1}{\sum_{j=1}^k \omega_{ij}}, \quad (35)$$

then the fractional hybrid system (1) is UH-stable and consequently, generalized UH-stable.

Proof: Let $\bar{p} \in \prod_{i=1}^k W_i$ is a solution of the inequality (34) and let $\bar{q} \in \prod_{i=1}^k W_i$ represent the unique solution of the problem

$$\begin{cases} D^{\alpha_1} \left(\frac{q_1(\tau)}{f_1(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau))} \right) = h_1(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau)), \\ D^{\alpha_2} \left(\frac{q_2(\tau)}{f_2(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau))} \right) = h_2(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau)), \\ \vdots \\ D^{\alpha_k} \left(\frac{q_k(\tau)}{f_k(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau))} \right) = h_k(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau)), \\ q_i(0) = p_i(0), i = 1, 2, \dots, k, \end{cases}$$

Applying Lemma 5, we can write

$$q_i(\tau) = f_i(\tau, \bar{q}(\tau))(I^{\alpha_i}[g_i^{q_i}(\tau)] + c_0), i = 1, 2, \dots, k,$$

where $g_i^{q_i}(\tau) = h_i(\tau, q_1(\tau), q_2(\tau), \dots, q_k(\tau)), i = 1, 2, \dots, k$.

By integration of the (34), we obtain

$$|p_i(t) - f_i(\tau, \bar{q}(\tau))(I^{\alpha_i}[g_i^{q_i}(\tau)] + d_0)| \leq \frac{v_i \tau^{\alpha_i}}{\Gamma(\alpha_i+1)} \leq \frac{v_i}{\Gamma(\alpha_i+1)}, i = 1, 2, \dots, k.$$

Thanks to $(A_j), j = 1, 2$, we can write

$$\begin{aligned} |p_i(\tau) - q_i(\tau)| &\leq |p_i(\tau) - f_i(\tau, \bar{q}(\tau))(I^{\alpha_i}[g_i^{q_i}(\tau)] + d_0)| \\ &\quad + |f_i(\tau, \bar{q}(\tau))| I^{\alpha_i}[|g_i^{p_i}(\tau) - g_i^{q_i}(\tau)|] \\ &\leq \frac{v_i}{\Gamma(\alpha_i+1)} + \frac{N_i}{\Gamma(\alpha_i+1)} \sum_{j=1}^k \omega_{ij} |p_j(s) - q_j(s)| ds, i = 1, 2, \dots, k, \end{aligned}$$

This implies that

$$\sum_{i=1}^k \|p_i - q_i\|_{W_i} \leq \sum_{i=1}^k \frac{v_i}{\Gamma(\alpha_i+1)} + \sum_{i=1}^k \frac{N_i}{\Gamma(\alpha_i+1)} \sum_{j=1}^k \omega_{ij} \|p_j - q_j\|_{W_i}.$$

Consequently, we obtain

$$\|\bar{p} - \bar{q}\|_{\prod_{i=1}^k W_i} \leq \frac{\sum_{i=1}^k \frac{1}{\Gamma(\alpha_i+1)}}{1 - \sum_{i=1}^k \frac{N_i}{\Gamma(\alpha_i+1)} \sum_{j=1}^k \omega_{ij}} v =: \eta_{f_i, h_i} v.$$

Hence, (1) is UH-stable.

If we put $\psi_{f_i, h_i}(\theta) = \eta_{f_i, h_i} \theta, \psi_{f_i, h_i}(0) = 0$, then hybrid system (1) is generalized UH-stable.

5. Application

Consider the following hybrid fractional system:

$$\begin{cases} D^{\alpha_1} \left(\frac{q_1(\tau)}{\frac{|\cos q_1(\tau)| + |\sin q_2(\tau)| + |\cos q_3(\tau)| + 3}{5}} \right) = \frac{\cos q_1(\tau) + \sin(q_2(\tau) + q_3(\tau))}{\pi e^{\tau} + 15} + \ln(1 + \tau^2), \tau \in \Phi, \\ D^{\alpha_2} \left(\frac{q_2(\tau)}{\frac{|\sin q_1(\tau)| + |\cos(q_2(\tau) + q_3(\tau))|}{13}} \right) = \frac{e^{-\tau^2} (e^{-|q_1(\tau)|} + \cos q_2(\tau) + \sin(2\pi q_2(\tau)))}{19\pi + e^{\tau^2}} + \cosh(2 + \tau^2), \tau \in \Phi, \\ D^{\alpha_3} \left(\frac{q_3(\tau)}{\frac{|\cos q_1(\tau)| + |\sin(q_2(\tau) + q_3(\tau))| + 2}{13}} \right) = \frac{\sin(2\pi q_1(\tau))}{32\pi} + \frac{\tan^{-1}(q_2(\tau) + q_3(\tau))}{16} + \cos^2 \tau + \tau^2 + 3, \tau \in \Phi, \\ q_i(0) = \theta_i \int_0^{\beta_i} e^{ir} q_i(r) dr, i = 1, 2, 3. \end{cases} \quad (36)$$

Here $\alpha_1 = \frac{1}{2}, \alpha_2 = \frac{1}{3}, \alpha_3 = \frac{2}{3}, \theta_1 = 5, \theta_2 = 7, \theta_3 = \frac{3}{5}, \beta_i = \frac{4}{5}, (i = 1, 2, 3), \varphi_i(\tau) = e^{i\tau}, \tau \in \Phi = [0, 1]$ and

$$\begin{aligned} f_1(\tau, q_1, q_2, q_3) &= \frac{|\cos q_1(\tau)| + |\sin q_2(\tau)| + |\cos q_3(\tau)| + 3}{5}, \\ f_2(\tau, q_1, q_2, q_3) &= \frac{|\sin q_1(\tau)| + |\cos(q_2(\tau) + q_3(\tau))|}{13}, \\ f_3(\tau, q_1, q_2, q_3) &= \frac{|\cos q_1(\tau)| + |\sin(q_2(\tau) + q_3(\tau))| + 2}{13}, \\ h_1(\tau, q_1, q_2, q_3) &= \frac{\cos q_1(\tau) + \sin(q_2(\tau) + q_3(\tau))}{\pi e^{\tau} + 15} + \ln(1 + \tau^2), \end{aligned}$$

$$h_2(\tau, q_1, q_2, q_3) = \frac{e^{-\tau^2} (e^{-|q_1(\tau)| + \cos w_2(\tau) + \sin(2\pi q_2(\tau))})}{19\pi + e^{\tau^2}} + \cosh(2 + \tau^2),$$

$$h_3(\tau, q_1, q_2, q_3) = \frac{\sin(2\pi q_1(\tau))}{32\pi} + \frac{\tan^{-1}(q_2(\tau)) + q_3(\tau)}{16} + \cos^2 \tau + \tau^2 + 3.$$

For $(q_1, q_2, q_3), (p_1, p_2, p_3) \in \mathbb{R}^3$ and $\tau \in [0, 1]$

$$|f_1(\tau, q_1, q_2, q_3)| \leq \frac{6}{5}, |f_2(\tau, q_1, q_2, q_3)| \leq \frac{2}{13}, |f_3(\tau, q_1, q_2, q_3)| \leq \frac{4}{13},$$

and

$$|h_1(\tau, q_1, q_2, q_3) - h_1(\tau, p_1, p_2, p_3)| \leq \frac{1}{\pi + 15} (|q_1 - p_1| + |q_2 - p_2| + |q_3 - p_3|),$$

$$|h_2(\tau, q_1, q_2, q_3) - h_2(\tau, p_1, p_2, p_3)| \leq \frac{1}{19\pi + 1} (|q_1 - p_1| + |q_2 - p_2| + |q_3 - p_3|),$$

$$|h_3(\tau, q_1, q_2, q_3) - h_3(\tau, p_1, p_2, p_3)| \leq \frac{1}{16} (|q_1 - p_1| + |q_2 - p_2| + |q_3 - p_3|).$$

We found $\Lambda_1; 1.192\ 3, \Lambda_2; 0.971\ 27, \Lambda_3; 1.131\ 5$ and we take $\omega_{11} = \omega_{12} = \omega_{13} = \frac{1}{\pi + 15}, \omega_{21} = \omega_{23} = \omega_{23} = \frac{1}{19\pi + 1}, \omega_{31} = \omega_{32} = \omega_{33} = \frac{1}{16}$.

Hence, we obtain

$$\sum_{i=1}^3 (\Lambda_i \sum_{j=1}^3 \omega_{ij}); 0.457\ 33 < 1,$$

and

$$\frac{\sum_{i=1}^k \frac{1}{\Gamma(\alpha_i + 1)}}{1 - \sum_{i=1}^k \frac{N_i}{\Gamma(\alpha_i + 1)} \sum_{j=1}^k \omega_{ij}} = 4.477\ 0.$$

Thanks to Theorem 6, the problem (36) admits a unique solution on $[0, 1]$. By Theorem 11, problem (36) is UH-stable with

$$\|\bar{p} - \bar{q}\|_{\prod_{i=1}^3 W_i} \leq 4.477\ \theta, v > 0.$$

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Received December, 2024