

Solution of special cases of PDEs with homogeneous terms

Sattar Naser Ketab *

Department of Mathematics

Faculty of Education

University of Kufa

Kufa

Najaf

Iraq

Banen Wafaa Abdullah [†]

Department of Mathematics

Faculty of Basic Education

University of Kufa

Kufa

Najaf

Iraq

Zainab Radhi Mousa [§]

Department of Computer Science

Faculty of Computer Science and Mathematics

University of Kufa

Kufa

Najaf

Iraq

Abstract

This study seeks to derive complete solutions for certain classes of third-order linear partial differential equations with constant coefficients involving three independent variables, expressed in the general form:

$$B_1 H_{ppp} + B_2 H_{ppn} + B_3 H_{pnn} + B_4 H_{nnn} + B_5 H_{ppm} + B_6 H_{pnm} + B_7 H_{pmm} + B_8 H_{nnm} + B_9 H_{nmm} + B_{10} H_{mmm} + B_{11} H_{pp} + B_{12} H_{pn} + B_{13} H_{pm} + B_{14} H_{nn} + B_{15} H_{nm} + B_{16} H_{mm} + B_{17} H_p + B_{18} H_n + B_{19} H_m + B_{20} H = 0.$$

* E-mail: sattar.alghazali@uokufa.edu.iq (Corresponding Author)

[†] E-mail: banenw.alfatlawy@uokufa.edu.iq

[§] E-mail: zainabr.almajtomy@uokufa.edu.iq

Based on this supposition, the above equation can be simplified to a third-degree nonlinear second-order ordinary differential equation with three free functions.

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1. Introduction

Various methods of solving partial differential equations (PDEs) have been suggested by many studies [1]. Other related contributions to differential equations are also available in [2-7]. In the current work, we explore functions that can be used to address the considered problem. $v(p)$, $k(n)$ and $u(m)$, $H(p, n, m) = e^{\int v(p)dp + \int k(n)dn + \int u(m)dm}$, Consequently, the general solution of the linear third-order partial differential equation with three independent variables is in the form as follows:

$$\begin{aligned} & B_1 H_{ppp} + B_2 H_{ppn} + B_3 H_{pnn} + B_4 H_{nnn} + B_5 H_{ppm} + B_6 H_{pmm} + B_7 H_{pnm} \\ & + B_8 H_{nnm} + B_9 H_{nmm} + B_{10} H_{mmm} + B_{11} H_{pp} + B_{12} H_{pn} + B_{13} H_{pm} + B_{14} H_{nn} \\ & + B_{15} H_{nm} + B_{16} H_{mm} + B_{17} H_p + B_{18} H_n + B_{19} H_m + B_{20} H = 0 \end{aligned}$$

Depending on the values, the original partial differential equations (PDEs) are reduced to a nonlinear second-order ordinary differential equation (ODE) in three independent variables.

2. On the Solution of Certain Classes of Linear Third-Order Partial Differential Equations with Constant Coefficients.

The general form of these equations is given by:

$$\begin{aligned} & B_1 H_{ppp} + B_2 H_{ppn} + B_3 H_{pnn} + B_4 H_{nnn} + B_5 H_{ppm} + B_6 H_{pmm} + B_7 H_{pnm} \\ & + B_8 H_{nnm} + B_9 H_{nmm} + B_{10} H_{mmm} + B_{11} H_{pp} + B_{12} H_{pn} + B_{13} H_{pm} + B_{14} H_{nn} \\ & + B_{15} H_{nm} + B_{16} H_{mm} + B_{17} H_p + B_{18} H_n + B_{19} H_m + B_{20} H = 0 \end{aligned}$$

To obtain the full answer, the equation will be divided into a few different cases as follows:

Case 1: $B_1 H_{ppp} + B_3 H_{pnn} + B_9 H_{nmm} = 0$. (i.e. $B_2 = B_4 = B_6 = \dots = B_8 = B_{10} = \dots = B_{20} = 0$) s.t. B_1, B_3 , and B_9 are not identically zero.

Case 2: $B_2 H_{ppn} + B_3 H_{pnn} + B_4 H_{nnn} + B_6 H_{pmm} = 0$. (i.e. $B_1 = B_5 = B_7 = \dots = B_{20} = 0$) s.t. B_2, B_3, B_4 and B_6 are not identically zero.

3. Proposals on Methodological Framework of the proposed Technique.

We consider a type of linear third-order partial equations of the form:

$$\begin{aligned} & B_1 H_{ppp} + B_2 H_{ppn} + B_3 H_{pnn} + B_4 H_{nnn} + B_5 H_{ppm} + B_6 H_{pmm} + B_7 H_{pnm} + \\ & B_8 H_{nnm} + B_9 H_{nmm} + B_{10} H_{mmm} + B_{11} H_{pp} + B_{12} H_{pn} + B_{13} H_{pm} + B_{14} H_{nn} \\ & + B_{15} H_{nm} + B_{16} H_{mm} + B_{17} H_p + B_{18} H_n + B_{19} H_m + B_{20} = 0 \quad (1) \end{aligned}$$

To get the complete solution we compute three independent functions under the following assumption.

$$H(p, n, m) = e^{\int v(p)dp + \int k(n)dn + \int u(m)dm} \quad (2)$$

by substituting

$$H, H_p, H_{pp}, H_{ppp}, H_{pn}, H_{ppn}, H_{pnn}, H_n, H_{nn}, H_m, H_{pm}, H_{nm}, H_{mm}, H_{ppm}, \\ H_{pmm}, H_{nnm}, H_{nmm}, H_{pnm}$$

and H_{mmm} into the equation (1), we get

$$B_1(v'' + 3vv' + v^3) + B_2k(v' + v^2) + B_3v(k' + k^2) + B_4(k'' + 3kk' + k^3) \\ + B_5u(v' + v^2) + B_6v(u' + u^2) + B_7vku + B_8u(k' + k^2) + B_9k(u' + u^2) \\ + B_{10}(u'' + 3uu' + u^3) + B_{11}(v' + v^2) + B_{12}vk + B_{13}vu + B_{14}(k' + k^2) \\ + B_{15}ku + B_{16}(u' + u^2) + B_{17}v + B_{18}k + B_{19}u + B_{20} = 0 \quad (3)$$

It is a nonlinear two-order ordinary differential equation with three independent functions, as presented in Equation (3).

4. On the Full Solution of the Linear Third-Order Partial Differential Equations.

The entire solution of the linear partial third-order partial equation with constant coefficients is established by re-examining the situations described in the beginning of this paper.

Case 1: If $B_2 = B_4 = B_6 = \dots = B_8 = B_{10} = \dots = B_{20} = 0$, $B_1H_{ppp} + B_3H_{pnn} + B_9H_{nmm} = 0$, then the equation (3) becomes

$$B_1(v'' + 3vv' + v^3) + B_3v(k' + k^2) + B_9k(u' + u^2) = 0.$$

$$\text{i) } (p, n, m) = e^{\gamma p + \frac{\delta^2 n}{2\gamma B_3}} \left[d_1 \cos \sqrt{\frac{B_1 \gamma^2}{B_3} - \left(\frac{\delta^2}{2\gamma B_3} \right)^2} n + \right.$$

$$\left. H d_2 \sin \sqrt{\frac{B_1 \gamma^2}{B_3} - \left(\frac{\delta^2}{2\gamma B_3} \right)^2} n \right] \left[d_3 \cos \frac{\delta}{\sqrt{B_9}} m + d_4 \sin \frac{\delta}{\sqrt{B_9}} m \right]$$

$$d_1 = A \cos(b_1 g_2), d_2 = A \sin(b_1 g_2), d_3 = \cos\left(\frac{\delta}{\sqrt{B_9}} g_1\right), d_4 = \sin\left(\frac{\delta}{\sqrt{B_9}} g_1\right).$$

Where $d_1, d_2, d_3, d_4, \delta$ and γ are arbitrary constants, if $\frac{B_1 \gamma^2}{B_3} \neq \left(\frac{\delta^2}{2\gamma B_3} \right)^2$.

$$\text{ii) } H(p, n, m) = (k - g) e^{\gamma p + \frac{\delta^2 n}{2\gamma B_3}} \left[d_3 \cos \frac{\delta}{\sqrt{B_9}} m + d_4 \sin \frac{\delta}{\sqrt{B_9}} m \right]$$

Where d_3, d_4, δ and γ are arbitrary constants, if $\frac{B_1 \gamma^2}{B_3} = \left(\frac{\delta^2}{2\gamma B_3} \right)^2$.

Proof: Since $B_1(v'' + 3vv' + v^3) + B_3v(k' + k^2) + B_9k(u' + u^2) = 0$.

Since we cannot use the separation of variables method we take representing to an arbitrary constant. This results in the simplified version of the equation:

$$\begin{aligned} B_1\gamma^3 + B_3\gamma(k' + k^2) + B_9k(u' + u^2) &= 0 \\ \Rightarrow \frac{B_1\gamma^3}{k} + B_3\gamma\left(\frac{k' + k^2}{k}\right) + B_9(u' + u^2) &= 0 \end{aligned}$$

This equation is variable separable equation [1], to solve it

Let

$$\frac{B_1\gamma^3}{k} + B_3\gamma\left(\frac{k' + k^2}{k}\right) = -B_9(u' + u^2) = -\delta^2$$

So:

$$\frac{B_1\gamma^3}{k} + B_3\gamma\left(\frac{k' + k^2}{k}\right) + \delta^2 = 0 \Rightarrow k' + k^2 + \frac{\delta^2}{\gamma B_3}k + \frac{B_1\gamma^2}{B_3} = 0 \quad (4)$$

also:

$$B_9(u' + u^2) - \delta^2 = 0 \Rightarrow u' + u^2 - \frac{\delta^2}{B_9} = 0 \quad (5)$$

From the equation (4): i) If $\frac{B_1\gamma^2}{B_3} \neq \left(\frac{\delta^2}{2\gamma B_3}\right)^2$, we get:

$$\begin{aligned} \frac{dk}{\left(k + \frac{\delta^2}{2\gamma B_3}\right)^2 + b_1^2} + dn &= 0; \quad b_1^2 = \frac{B_1\gamma^2}{B_3} - \left(\frac{\delta^2}{2\gamma B_3}\right)^2 \\ \Rightarrow \frac{1}{b_1} \tan^{-1} \left[\frac{k + \frac{\delta^2}{2\gamma B_3}}{b_1} \right] &= g_1 - n \Rightarrow k = b_1 \tan(b_1 g_1 - b_1 n) - \frac{\delta^2}{2\gamma B_3} \end{aligned} \quad (6)$$

And from equation (5), we get $\frac{du}{u^2 + \frac{\delta^2}{B_9}} + dm = 0 \Rightarrow \frac{B_9}{\delta^2} \frac{du}{\left(\frac{\sqrt{B_9}}{\delta}u\right)^2 + 1} + dm = 0$

$$\Rightarrow \frac{\sqrt{B_9}}{\delta} \tan^{-1} \left(\frac{\sqrt{B_9}}{\delta} u \right) = g_2 - m \Rightarrow u = \frac{\delta}{\sqrt{B_9}} \tan \left(\frac{\delta}{\sqrt{B_9}} g_2 - \frac{\delta}{\sqrt{B_9}} m \right) \quad (7)$$

$$H(p, n, m) = e^{\int \gamma dp + \int [b_1 \tan(b_1 g_2 - b_1 n) - \frac{\delta^2}{2\gamma B_3}] dn + \int \left[\frac{\beta}{\sqrt{B_9}} \tan \left(\frac{\delta}{\sqrt{B_9}} g - \frac{\delta}{\sqrt{B_9}} m \right) \right] dm}$$

$$H(p, n, m) = A [\cos(b_1 g_2 - b_1 n)] \cos \left(\frac{\delta}{\sqrt{B_9}} g_1 - \frac{\delta}{\sqrt{B_9}} m \right) e^{\gamma p - \frac{\delta^2}{2\gamma B_3} n}; \quad A = e^h$$

And the complete solution is given by:

$$\begin{aligned} H(p, n, m) &= e^{\gamma p - \frac{\delta^2}{2\gamma B_3} n} [d_1 \cos \sqrt{\frac{B_1\gamma^2}{B_3} - \left(\frac{\beta^2}{2\gamma B_3}\right)^2} n + \\ &\quad d_2 \sin \sqrt{\frac{B_1\gamma^2}{B_3} - \left(\frac{\beta^2}{2\gamma B_3}\right)^2} n] [d_3 \cos \frac{\delta}{\sqrt{B_9}} m + d_4 \sin \frac{\delta}{\sqrt{B_9}} m] \end{aligned}$$

$$d_1 = A \cos(b_1 g_2), d_2 = A \sin(b_1 g_2), d_3 = \cos \left(\frac{\delta}{\sqrt{B_9}} g_1 \right), d_4 = \sin \left(\frac{\delta}{\sqrt{B_9}} g_1 \right).$$

Where $d_1, d_2, d_3, d_4, \delta$ and γ are arbitrary constants.

ii) If $\frac{B_1\gamma^2}{B_3} = \left(\frac{\delta^2}{2\gamma B_3}\right)^2$ we get

$$\frac{dk}{\left(k + \frac{\delta^2}{2\gamma B_3}\right)^2} + dn = 0 \Rightarrow \frac{-1}{k + \frac{\delta^2}{2\gamma B_3}} = g_3 - n \Rightarrow k = \frac{1}{n - g_3} - \frac{\delta^2}{2\gamma B_3} \quad (8)$$

And

$$u = \frac{\delta}{\sqrt{B_9}} \tan\left(\frac{\delta}{\sqrt{B_9}} g_2 - \frac{\delta}{\sqrt{B_9}} m\right),$$

so,

$$H(p, n, m) = e^{\int \gamma dp + \int \left[\frac{1}{n-g_3} - \frac{\delta^2}{2\gamma B_3}\right] dn + \int \left[-\frac{\delta}{\sqrt{B_9}} \tan\left(\frac{\delta}{\sqrt{B_9}} g_2 - \frac{\delta}{\sqrt{B_9}} m\right)\right] dm}$$

$$H(p, n, m) = A(n - g_3) e^{\gamma p - \frac{\delta^2}{2\gamma B_3} n} \left[\cos\left(\frac{\delta}{\sqrt{B_9}} g_2 - \frac{\delta}{\sqrt{B_9}} m\right) \right]; A = e^h,$$

The complete solution is given by:

$$H(p, n, m) = A(n - g) e^{\gamma p - \frac{\delta^2}{2\gamma B_3} n} \left[d_3 \cos \frac{\delta}{\sqrt{B_9}} m + d_4 \sin \frac{\delta}{\sqrt{B_9}} m \right]$$

Case 2: If $B_1 = B_5 = B_7 = \dots = B_{20} = 0$, given by: $B_2 H_{ppn} + B_3 H_{pnn} + B_4 H_{nnn} + B_6 H_{pmm} = 0$, then the equation (3) becomes

$$B_2 k(v' + v^2) + B_3 v(k' + k^2) + B_4(k'' + 3kk' + k^3) + B_6 v(u' + u^2) = 0.$$

$$\begin{aligned} \text{i)} \quad H(p, n, m) &= e^{-\frac{\delta^2}{2\gamma B_2} p + \gamma n} \left[d_1 \cos \sqrt{\frac{B_4 \gamma^2}{B_2} - \left(\frac{\delta^2}{2\gamma B_2}\right)} p + \right. \\ &\quad \left. d_2 \sin \sqrt{\frac{B_4 \gamma^2}{B_2} - \left(\frac{\delta^2}{2\gamma B_2}\right)} p \right] \left[d_3 \cos \left(\sqrt{\frac{\delta^2 - \gamma^2 B_3}{B_6}} m \right) + d_4 \sin \left(\sqrt{\frac{\delta^2 - \gamma^2 B_3}{B_6}} m \right) \right]; \\ d_1 &= \cos(b_2 g_4), d_2 = \sin(b_2 g_4), d_3 = \cos\left(\sqrt{\frac{B_3 \gamma^2 - \delta^2}{B_6}} g_5\right), \end{aligned}$$

$$\text{i)} \quad d_4 = \sin\left(\sqrt{\frac{B_3 \gamma^2 - \delta^2}{B_6}} g_5\right).$$

Where $d_1, d_2, d_3, d_4, \delta$ and γ are arbitrary constants, if $\frac{B_4 \gamma^2}{B_2} \neq \left(\frac{\delta^2}{2\gamma B_2}\right)^2$.

$$\begin{aligned} \text{ii)} \quad H(p, n, m) &= A(p - g) e^{-\frac{\delta^2}{2\gamma B_2} p + \gamma n} \\ &\quad \left[d_3 \cos \left(\sqrt{\frac{\delta^2 - \gamma^2 B_3}{B_6}} m \right) + d_4 \sin \left(\sqrt{\frac{\delta^2 - \gamma^2 B_3}{B_6}} m \right) \right]; A = e^h \\ d_3 &= \cos\left(\sqrt{\frac{B_3 \gamma^2 - \delta^2}{B_6}} g_6\right), d_4 = \sin\left(\sqrt{\frac{B_3 \gamma^2 - \delta^2}{B_6}} g_6\right) \end{aligned}$$

Where d_3, d_4, A, δ and γ are arbitrary constants, if $\frac{B_4 \gamma^2}{B_2} = \left(\frac{\delta^2}{2\gamma B_2}\right)^2$.

Proof: Since $B_2 k(v' + v^2) + B_3 v(k' + k^2) + B_4(k'' + 3kk' + k^3) + B_6 v(u' + u^2) = 0$, $B_2 \gamma(v' + v^2) + B_3 \gamma^2 v + B_4 \gamma^3 + B_6 v(u' + u^2) = 0$

$$\Rightarrow B_2 \gamma \left(\frac{v' + v^2}{v}\right) + B_3 \gamma^2 + \frac{B_4 \gamma^3}{v} + B_6 (u' + u^2) = 0.$$

$$B_2 \gamma \left(\frac{v' + v^2}{v}\right) + \frac{B_4 \gamma^3}{v} = -B_3 \gamma^2 - B_6 (u' + u^2) = -\delta^2$$

So:

$$B_2\gamma\left(\frac{v'+v^2}{v}\right) + \frac{B_4\gamma^3}{v} + \delta^2 = 0 \Rightarrow v' + v^2 + \frac{\delta^2}{B_2\gamma}v + \frac{B_4\gamma^2}{B_2} = 0 \quad (9)$$

also:

$$B_3\gamma^2 + B_6(u' + u^2) - \delta^2 = 0 \Rightarrow u' + u^2 + \frac{B_3\gamma^2 - \delta^2}{B_6} = 0 \quad (10)$$

From the equation (9): i) If $\frac{B_4\gamma^2}{B_2} \neq \left(\frac{\delta^2}{2\gamma B_2}\right)^2$, we get

$$\begin{aligned} \frac{dv}{\left(v + \frac{\delta^2}{2\gamma B_2}\right)^2 + b_2^2} + dp = 0; \quad b_2^2 = \frac{B_4\gamma^2}{B_2} - \left(\frac{\delta^2}{2\gamma B_2}\right)^2, \\ \Rightarrow \frac{1}{b_2} \tan^{-1}\left(\frac{v + \frac{\delta^2}{2\gamma B_2}}{b_2}\right) = g_4 - p \Rightarrow v = b_2 \tan(b_2 g_4 - b_2 p) - \frac{\delta^2}{2\gamma B_2} \end{aligned} \quad (11)$$

From the equation (10), we get

$$\begin{aligned} \frac{du}{u^2 + \frac{B_3\gamma^2 - \delta^2}{B_6}} + dm = 0 \Rightarrow \frac{B_6}{B_3\gamma^2 - \delta^2} \frac{du}{\left(\sqrt{\frac{B_6}{B_3\gamma^2 - \delta^2}}u\right)^2 + 1} + dm = 0 \\ \Rightarrow \sqrt{\frac{B_6}{B_3\gamma^2 - \delta^2}} \tan^{-1}\left(\sqrt{\frac{B_6}{B_3\gamma^2 - \delta^2}}u\right) = g_5 - m \\ \Rightarrow u = \sqrt{\frac{B_3\gamma^2 - \delta^2}{B_6}} \tan\left(\sqrt{\frac{B_3\gamma^2 - \delta^2}{B_6}}g_5 - \sqrt{\frac{B_3\gamma^2 - \delta^2}{B_6}}m\right) \end{aligned} \quad (12)$$

So,

$H(p, n, m)$

$$= e^{\int [b_2 \tan(b_2 g_4 - b_2 p) - \frac{\delta^2}{2\gamma B_2}] dp + \int \gamma dn + \int \left[\sqrt{\frac{B_3\gamma^2 - \delta^2}{B_6}} \tan\left(\sqrt{\frac{B_3\gamma^2 - \delta^2}{B_6}}g_5 - \sqrt{\frac{B_3\gamma^2 - \delta^2}{B_6}}m\right) \right] dm}$$

$$H(p, n, m) = A \cos(b_2 g_4 - b_2 p) \cos\left(\sqrt{\frac{B_3\gamma^2 - \delta^2}{B_6}}g_5 - \sqrt{\frac{B_3\gamma^2 - \delta^2}{B_6}}m\right) e^{-\frac{\delta^2}{2\gamma B_2}p + \gamma n}$$

$$A = e^h.$$

And the complete solution is given by:

$$\begin{aligned} H(p, n, m) = e^{-\frac{\delta^2}{2\gamma B_2}p + \gamma n} \left[d_1 \cos\sqrt{\frac{B_4\gamma^2}{B_2} - \left(\frac{\delta^2}{2\gamma B_2}\right)^2} p + \right. \\ \left. d_2 \sin\sqrt{\frac{B_4\gamma^2}{B_2} - \left(\frac{\delta^2}{2\gamma B_2}\right)^2} p \right] \left[d_3 \cos\left(\sqrt{\frac{B_3\gamma^2 - \delta^2}{B_6}}m\right) + d_4 \sin\left(\sqrt{\frac{B_3\gamma^2 - \delta^2}{B_6}}m\right) \right] \end{aligned}$$

Where $d_1, d_2, d_3, d_4, \delta$ and γ are arbitrary constants.

ii) If $\frac{B_4\gamma^2}{B_2} = \left(\frac{\delta^2}{2\gamma B_2}\right)^2$, we get: From (9)

$$\frac{dv}{\left(v + \frac{\delta^2}{2\gamma B_2}\right)^2} + dp = 0 \Rightarrow \frac{-1}{v + \frac{\delta^2}{2\gamma B_2}} = g_6 - p \Rightarrow v = \frac{1}{p - g_6} - \frac{\delta^2}{2\gamma B_2} \quad (13)$$

And

$$u = \sqrt{\frac{B_3\gamma^2 - \delta^2}{B_6}} \tan\left(\sqrt{\frac{B_3\gamma^2 - \delta^2}{B_6}}g_6 - \sqrt{\frac{B_3\gamma^2 - \delta^2}{B_6}}m\right)$$

so,

$$H(p, n, m) = e^{\int [\frac{1}{p-g_5} - \frac{\delta^2}{2\gamma B_2}] dp + \int \gamma dn + \int [\sqrt{\frac{B_3 \gamma^2 - \delta^2}{B_6}} \tan(\sqrt{\frac{B_3 \gamma^2 - \delta^2}{B_6}} g_6 - \sqrt{\frac{B_3 \gamma^2 - \delta^2}{B_6}} m)] dm}$$

so, the complete solution is given by:

$$H(p, n, m) = A(p - g_5) e^{-\frac{\delta^2}{2\gamma B_2} p + \gamma n} [d_3 \cos(\sqrt{\frac{B_3 \gamma^2 - \delta^2}{B_6}} m) + d_4 \sin(\sqrt{\frac{B_3 \gamma^2 - \delta^2}{B_6}} m)] ; A = e^h$$

Example 4.1: To find a solution to the following partial differential equation:

$$3H_{ppp} - \frac{1}{4}H_{pnn} + 2H_{nmm} = 0, B_1 = 3, B_3 = -\frac{1}{4}, B_9 = 2.$$

Since $\frac{B_1 \gamma^2}{B_3} \neq (\frac{\delta^2}{2\gamma B_3})^2$, then by using the formula (as in case-1-i)

$$H(p, n, m) = e^{\gamma p - \frac{\delta^2}{2\gamma B_3} n} [d_1 \cos \sqrt{-12\gamma^2 - \frac{4\delta^4}{\gamma^2}} n + d_2 \sin \sqrt{-12\gamma^2 - \frac{4\delta^4}{\gamma^2}} n] [d_3 \cos \frac{\delta}{\sqrt{2}} m + d_4 \sin \frac{\delta}{\sqrt{2}} m]$$

Where $d_1, d_2, d_3, d_4, \delta$.

Conclusion

This study presented complete solutions for certain classes of third-order linear partial differential equations with constant coefficients involving three independent variables. The original equation was reduced to a third-degree nonlinear second-order ordinary differential equation with three free functions, providing a simplified and effective approach for solving such equations.

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