

$\mathbb{J}$ -focal nested set

Maryam Khenyab Kareem *

L. A. A. Jabar [†]

Department of Mathematics

College of Education for Pure Sciences

University of Babylon

Babylon

Iraq

Abstract

In this work, we derived two new mathematical concepts in $\mathbb{J}$ -topological spaces with significant effects on topological concepts, which are ($\mathbb{J}$ -focal nested set, $\mathbb{J}$ -focal ingrained set), and were constructed based on the grill and its properties. The most important properties of both were highlighted by providing various examples and an intensive study of their shared and interrelated properties.

Subject Classification: 05C10, 06B30.

Keywords: $\mathbb{J}$ -focal, $\mathbb{J}$ -nested, $\mathbb{J}$ - ingrained, $\mathbb{J}$ -focal nested set, $\mathbb{J}$ -focal ingrained set.

1. Introduction

The topological mathematical concepts of various types (interior, exterior, bounded, closure,) appear in multiple forms depending on the topological space or the shape of the space. Many scientists and researchers have studied these properties in various spaces such as metric spaces (X, d) and proximity spaces (X, δ) , which is a bold generalization of metric spaces and is considered a qualitative leap in scientific research, especially in its applied field, as defined by Riesz in 1909 [1]. These concepts have also been studied concerning i -topological and $\mathbb{J}$ -topological space particularly in relation to adherent points, which were termed by the local function defined by Kuratowski in 1933[2]. Then, the researcher Yazici studied it concerning the ideal proximity space, and specific mathematical concepts emerged, which he referred to (focal and nested) [3]. The researcher Ali studied the concepts occlusion set via

* E-mail: pure652.mariem.khnyab@student.uobabylon.edu.iq (Corresponding Author)

[†] E-mail: l.h.jabar64@gmail.com

i – open set [4], while the researcher Raghad moved on to study local functions in spaces proximity, which introduced new concepts as well as follower set, takeoff set, sporadic family [5-8]. From here, the work became parallel and coordinated to extract and derive concepts, and this research specialized in the concept of focal sets.

2. Basic definitions and concepts

Definition 2.1: [6] Let $\mathcal{J}$ is a family of a non-empty set in topological space is called a grill if satisfies two conditions: 1. $\mathcal{S} \in \mathcal{J}$ and $\mathcal{S} \subseteq \mathcal{R} \subseteq \mathcal{K} \Rightarrow \mathcal{R} \in \mathcal{J}$ 2. if $\mathcal{S} \cup \mathcal{R} \in \mathcal{J}$ for $\mathcal{S}, \mathcal{R} \subseteq \mathcal{K}$, then $\mathcal{S} \in \mathcal{J}$ or $\mathcal{R} \in \mathcal{J}$.

Definition 2.2: Let $\mathcal{J}$ be a grill define on a nonempty set $\mathcal{K}$, the binary relation $\approx$ defined on $\mathcal{K}$ as follow: $\mathcal{S} \approx \mathcal{R}$ if and only if $(\mathcal{S} - \mathcal{R}) \cup (\mathcal{R} - \mathcal{S}) \notin \mathcal{J}$.

Example 2.3: $\mathcal{K} = \{\mathcal{S}, \mathcal{r}, \mathcal{c}\}$ and $\mathcal{J} = \{\mathcal{K}, \{\mathcal{r}\}, \{\mathcal{S}, \mathcal{r}\}, \{\mathcal{r}, \mathcal{c}\}\}$, $\mathcal{S} = \{\mathcal{S}\}$, $\mathcal{R} = \{\mathcal{S}, \mathcal{r}\}$ $\mathcal{S} \approx \mathcal{R}$ because $(\mathcal{S} - \mathcal{R}) \cup (\mathcal{R} - \mathcal{S}) = (\{\mathcal{S}\} - \{\mathcal{S}, \mathcal{r}\}) \cup (\{\mathcal{S}, \mathcal{r}\} - \{\mathcal{S}\}) = \{\mathcal{r}\} \notin \mathcal{J}$.

Definition 2.4: Let $\mathcal{J}$ be a grill, a $\mathcal{J}$ – topological space on $\mathcal{K}$ is a family $\mathcal{T}_{\mathcal{J}}$ of a subset of $\mathcal{K}$ that satisfies the conditions:

1. $\mathcal{K}, \emptyset \in \mathcal{T}_{\mathcal{J}}$.
2. Every $\mathcal{U} \subseteq \mathcal{T}_{\mathcal{J}}$, there exist $\mathcal{E} \in \mathcal{T}_{\mathcal{J}}$ such that $\bigcup \mathcal{U} \approx \mathcal{E}$.
3. Every $\mathcal{U}, \mathcal{E} \in \mathcal{T}_{\mathcal{J}}$, there exist $\mathcal{H} \in \mathcal{T}_{\mathcal{J}}$ such that $\mathcal{U} \cap \mathcal{E} \approx \mathcal{H}$.
4. $\mathcal{T}_{\mathcal{J}} \cap (\mathcal{P}(\mathcal{K}) \setminus \mathcal{J}) = \{\emptyset\}$.

Definitions 2.5: Let $\mathcal{K}_{\mathcal{J}}^{\mathcal{T}_{\mathcal{J}}}$ be $\mathcal{J}$ – topological space. Then, $\mathcal{K}_{\mathcal{J}}^{\mathcal{T}_{\mathcal{J}}}$ is called advanced $\mathcal{J}$ – topological space if it is closed under the intersection.

Definition 2.6: [7] A binary relation δ defined on the power set of $\mathcal{K}$ is called proximity on $\mathcal{K}$ if and only if it satisfies the following axioms:

1. $\mathcal{S}\delta\mathcal{R}$ implies $\mathcal{R}\delta\mathcal{S}$
2. $\mathcal{S} \cup \mathcal{R}\delta\mathcal{E}$ if and only if $\mathcal{S}\delta\mathcal{E}$ or $\mathcal{R}\delta\mathcal{E}$
3. $\mathcal{S}\delta\mathcal{R}$ implies $\mathcal{A} \neq \emptyset$ and $\mathcal{R} \neq \emptyset$
4. $\mathcal{S} \cap \mathcal{R} \neq \emptyset$ implies $\mathcal{S}\delta\mathcal{R}$
5. $\mathcal{S}\delta\mathcal{R}$ implies there exists a subset $\mathcal{U}$ of $\mathcal{K}$ such that $\mathcal{S}\bar{\delta}\mathcal{U}$ and $\mathcal{K} - \mathcal{U}\bar{\delta}\mathcal{R}$.

The pair $(\mathcal{K}, \delta)$ is called a proximity space.

Proposition 2.7: [7] Let $(\mathcal{K}, \delta)$ be a proximity space then:

1. If $\mathcal{R}\delta\mathcal{E}$, then $\mathcal{S}\delta\mathcal{E}$ where $\mathcal{R} \subseteq \mathcal{S}$.
2. If $\mathcal{R}\delta\mathcal{E}$, then $\mathcal{R}\delta\mathcal{H}$ where $\mathcal{E} \subseteq \mathcal{H}$.
3. If $\mathcal{R}\bar{\delta}\mathcal{E}$, then $\mathcal{R}\bar{\delta}\mathcal{H}$ where $\mathcal{H} \subseteq \mathcal{E}$.

Definition 2.8: The quadruple $(K_{\mathbb{L}}^{T_{\mathbb{L}}}, \delta)$ is called $\mathbb{L}$ -topological proximity space where $K_{\mathbb{L}}^{T_{\mathbb{L}}}$ is a $\mathbb{L}$ -topological space and (K, δ) is a proximity space.

Definition 2.9: Let $K_{\mathbb{L}}^{T_{\mathbb{L}}}$ be a $\mathbb{L}$ -topological space, then a subset S is named a $\mathbb{L}$ -focal set of a point $k \in K$, if there exist $U \in T_{\mathbb{L}}(k)$ such that $U \approx S$. The system of all $\mathbb{L}$ -focal sets of point k is denoted by $\mathbb{L}_{\delta}(k) = \{S \subseteq K : \exists U \in T_{\mathbb{L}}(k), U \approx S\}$.

Example 2.10: Let $K = \{s, r, c\}$, $T_{\mathbb{L}} = \{\emptyset, K, \{s, r\}, \{s, c\}\}$ and $\mathbb{L} = \{K, \{s\}, \{s, r\}, \{s, c\}\}$, $T_{\mathbb{L}}(s) = \{K, \{s, r\}, \{s, c\}\}$, $T_{\mathbb{L}}(r) = \{K, \{s, r\}\}$, $T_{\mathbb{L}}(c) = \{K, \{s, c\}\}$, $\mathcal{P}(K) = \{\emptyset, \{s\}, \{r\}, \{c\}, \{s, r\}, \{r, c\}, \{s, c\}\}$, $\mathbb{L}_{\delta}(s) = \mathbb{L}_{\delta}(r) = \mathbb{L}_{\delta}(c) = \{\{s\}, \{s, r\}, \{s, c\}, K\}$.

Theorem 2.11: Let $X_{\mathbb{L}}^{T_{\mathbb{L}}}$ be a $\mathbb{L}$ -topological space and $A, B \subseteq X$, then each of the following properties are holds:

1. For every $A \in T_{\mathbb{L}}(x)$, then $A \in \mathbb{L}_{\delta}(x)$ and $\emptyset \notin \mathbb{L}_{\delta}(x)$.
2. If $A \in \mathbb{L}_{\delta}(x)$, then $X - A \notin \mathbb{L}_{\delta}(x)$.

Proposition 2.12: Let $X_{\mathbb{L}_i}^{T_{\mathbb{L}_i}}$, $i = 1, 2$ be a $\mathbb{L}$ -topological spaces such that $T_{2\mathbb{L}_2}$ is finer than $T_{1\mathbb{L}_1}$, $\mathbb{L}_2$ is finer than $\mathbb{L}_1$, then:

1. $\mathbb{L}_{\delta}^{T_{2\mathbb{L}_2}}(x) \subseteq \mathbb{L}_{\delta}^{T_{1\mathbb{L}_1}}(x)$.
2. $\mathbb{L}_{2\delta}^{T_{2\mathbb{L}_2}}(x) \subseteq \mathbb{L}_{1\delta}^{T_{1\mathbb{L}_1}}(x)$.

Definition 2.13: Let $(K_{\mathbb{L}}^{T_{\mathbb{L}}}, \delta)$ be a $\mathbb{L}$ -topological proximity space then a point k of K is called a $\mathbb{L}$ -nested point of a subset S of K if there exist a proper subset U of K such that $U \in T_{\mathbb{L}}(k)$ and $U \delta S$.

The set of all $\mathbb{L}$ -nested points of K is called a $\mathbb{L}$ -nested set denoted by $N_{T_{\mathbb{L}}}(S) = \{k \in K : \exists K \neq U \in T_{\mathbb{L}}(k), U \delta S\}$.

By example 2.10, δ is proximity define by: $S \delta R \forall S \neq \emptyset, R \neq \emptyset$ except the relation: $\{s\} \delta \{r, c\}, \{r, c\} \delta \{s\}, \{s\} \delta \{r\}, \{r\} \delta \{s\}, \{s\} \delta \{c\}, \{c\} \delta \{s\}, S = \{s\}$, $N_{T_{\mathbb{L}}}(S) = \{\{s, r\}, \{s, c\}\}$.

Proposition 2.14: Let $(K_{\mathbb{L}}^{T_{\mathbb{L}}}, \delta)$ be a $\mathbb{L}$ -topological proximity space and let $S, R \subseteq K$, then each of the following properties are holds :

1. $S \subseteq R$, then $N_{T_{\mathbb{L}}}(S) \subseteq N_{T_{\mathbb{L}}}(R)$
2. $N_{T_{\mathbb{L}}}(S \cap R) \subseteq N_{T_{\mathbb{L}}}(S) \cap N_{T_{\mathbb{L}}}(R)$
3. $N_{T_{\mathbb{L}}}(S) \cup N_{T_{\mathbb{L}}}(R) = N_{T_{\mathbb{L}}}(S \cup R)$

4. If $\mathcal{S} \in \mathcal{T}_{\mathbb{L}}$, then $\mathcal{S} \subseteq \mathcal{N}_{\mathbb{L}}(\mathcal{S})$.

5. $\mathcal{N}_{\mathbb{L}}(\mathcal{S}) \subseteq \mathcal{S}$.

Definition 2.15: Let $(\mathcal{K}_{\mathbb{L}}^{\mathcal{T}_{\mathbb{L}}}, \delta)$ be a $\mathbb{L}$ -topological proximity space, then k in $\mathcal{K}$ is called an ingrained point of a subset $\mathcal{U}$ of $\mathcal{K}$ such that $\mathcal{U} \in \mathcal{T}_{\mathbb{L}}(k)$ and $\mathcal{U} \bar{\delta} \mathcal{K} \setminus \mathcal{S}$.

The set of all ingrained points of $\mathcal{K}$ is called an ingrained set denoted by $\mathcal{C}_{\mathbb{L}}(\mathcal{S}) = \{k \in \mathcal{K} : \forall \mathcal{K} \neq \mathcal{U} \in \mathcal{T}_{\mathbb{L}}(k), \mathcal{U} \bar{\delta} \mathcal{K} \setminus \mathcal{S}\}$.

By example 2.10, δ is a proximity define by: $\mathcal{S} \delta \mathcal{R} \forall \mathcal{S} \neq \emptyset, \mathcal{R} \neq \emptyset$ except the relation : $\{\mathcal{S}\} \bar{\delta} \{\mathcal{r}, \mathcal{c}\}, \{\mathcal{r}, \mathcal{c}\} \bar{\delta} \{\mathcal{S}\}, \{\mathcal{S}\} \bar{\delta} \{\mathcal{r}\}, \{\mathcal{r}\} \bar{\delta} \{\mathcal{S}\}, \{\mathcal{S}\} \bar{\delta} \{\mathcal{c}\}, \{\mathcal{c}\} \bar{\delta} \{\mathcal{S}\}, \mathcal{S} = \{\mathcal{S}\}, \mathcal{K} \setminus \mathcal{S} = \{\mathcal{r}, \mathcal{c}\} \mathcal{C}_{\mathbb{L}}(\mathcal{S}) = \emptyset$.

3. The $\mathbb{L}$ -focal nested set

Definition 3.1: Let $(\mathcal{K}_{\mathbb{L}}^{\mathcal{T}_{\mathbb{L}}}, \delta)$ be a $\mathbb{L}$ -topological proximity space then a point $k \in \mathcal{K}$ is called a $\mathbb{L}$ -focal nested point of $\mathcal{S} \subseteq \mathcal{K}$ if and only if there exist $\mathcal{U} \in \mathbb{L}_{\mathcal{S}}(k)$ is a proper subset of $\mathcal{K}, k \in \mathcal{U}$ such that $\mathcal{U} \delta \mathcal{S}$. The set of all $\mathbb{L}$ -focal nested points of a set $\mathcal{S}$ is called a $\mathbb{L}$ -focal nested set and denoted by $\mathcal{N}_{\mathbb{L}_{\mathcal{S}}}(\mathcal{S})$, i.e $\mathcal{N}_{\mathbb{L}_{\mathcal{S}}}(\mathcal{S}) = \{k \in \mathcal{K} : \exists \mathcal{U} \in \mathbb{L}_{\mathcal{S}}(k), \mathcal{U} \delta \mathcal{S}\}$ where $\mathbb{L}_{\mathcal{S}}(k) = \{\mathcal{U} \in \mathbb{L}_{\mathcal{S}}(k), k \in \mathcal{U}\}$.

- $k \notin \mathcal{N}_{\mathbb{L}_{\mathcal{S}}}(\mathcal{S})$ if and only if $\forall \mathcal{K} \neq \mathcal{U} \in \mathbb{L}_{\mathcal{S}}(k), \mathcal{U} \bar{\delta} \mathcal{S}$.

By example 2.10, δ is proximity define by: $\mathcal{S} \delta \mathcal{R} \forall \mathcal{S} \neq \emptyset, \mathcal{R} \neq \emptyset$ except the relation: $\{\mathcal{S}\} \bar{\delta} \{\mathcal{r}, \mathcal{c}\}, \{\mathcal{r}, \mathcal{c}\} \bar{\delta} \{\mathcal{S}\}, \{\mathcal{S}\} \bar{\delta} \{\mathcal{r}\}, \{\mathcal{r}\} \bar{\delta} \{\mathcal{S}\}, \{\mathcal{S}\} \bar{\delta} \{\mathcal{c}\}, \{\mathcal{c}\} \bar{\delta} \{\mathcal{S}\}, \mathcal{S} = \{\mathcal{S}\}, \mathcal{N}_{\mathbb{L}_{\mathcal{S}}}(\mathcal{S}) = \{\{\mathcal{S}\}, \{\mathcal{S}, \mathcal{r}\}, \{\mathcal{S}, \mathcal{c}\}\}$.

The relation between the two types of $\mathbb{L}$ -nested set is discussed below

Proposition 3.2: Let $(\mathcal{K}_{\mathbb{L}}^{\mathcal{T}_{\mathbb{L}}}, \delta)$ be a $\mathbb{L}$ -topological proximity space then $\mathcal{N}_{\mathbb{L}}(\mathcal{S}) \subseteq \mathcal{N}_{\mathbb{L}_{\mathcal{S}}}(\mathcal{S})$ for each subset $\mathcal{S}$ of $\mathcal{K}$.

Proof: Let $k \in \mathcal{N}_{\mathbb{L}}(\mathcal{S})$ by definition 2.14 $\exists \mathcal{K} \neq \mathcal{U} \in \mathcal{T}_{\mathbb{L}}(k)$, such that $\mathcal{U} \delta \mathcal{S}$ and by theorem (2.12 part (1)) we have $\mathcal{U} \in \mathbb{L}_{\mathcal{S}}(k)$, hence $k \in \mathcal{N}_{\mathbb{L}_{\mathcal{S}}}(\mathcal{S})$.

The converse of above proposition is not necessary true by example 2.10, δ is proximity define by: $\mathcal{S} \delta \mathcal{R} \forall \mathcal{S} \neq \emptyset, \mathcal{R} \neq \emptyset$ except the relation : $\{\mathcal{S}\} \bar{\delta} \{\mathcal{r}, \mathcal{c}\}, \{\mathcal{r}, \mathcal{c}\} \bar{\delta} \{\mathcal{S}\}, \{\mathcal{S}\} \bar{\delta} \{\mathcal{r}\}, \{\mathcal{r}\} \bar{\delta} \{\mathcal{S}\}, \{\mathcal{S}\} \bar{\delta} \{\mathcal{c}\}, \{\mathcal{c}\} \bar{\delta} \{\mathcal{S}\}, \mathcal{S} = \{\mathcal{S}\}, \mathcal{N}_{\mathbb{L}}(\mathcal{S}) = \{\{\mathcal{S}, \mathcal{r}\}, \{\mathcal{S}, \mathcal{c}\}\}, \mathcal{N}_{\mathbb{L}_{\mathcal{S}}}(\mathcal{S}) = \{\{\mathcal{S}\}, \{\mathcal{S}, \mathcal{r}\}, \{\mathcal{S}, \mathcal{c}\}\}, \mathcal{N}_{\mathbb{L}}(\mathcal{S}) \subseteq \mathcal{N}_{\mathbb{L}_{\mathcal{S}}}(\mathcal{S})$ but $\mathcal{N}_{\mathbb{L}_{\mathcal{S}}}(\mathcal{S}) \not\subseteq \mathcal{N}_{\mathbb{L}}(\mathcal{S})$.

Note 3.3: Let $(\mathcal{K}_{\mathbb{L}}^{\mathcal{T}_{\mathbb{L}}}, \delta)$ be a $\mathbb{L}$ -topological proximity space and $\mathcal{S} \subseteq \mathcal{K}$, then for some $k \in \mathcal{S}, \mathcal{N}_{\mathbb{L}_{\mathcal{S}}}(\mathcal{S}) \subseteq \mathcal{U} \{ \mathcal{U} \in \mathbb{L}_{\mathcal{S}}(k) : \mathcal{U} \subsetneq \mathcal{K}, \mathcal{U} \delta \mathcal{S} \}$.

Proof: Let $k \in N_{\mathbb{L}_\delta}(\mathcal{S})$ such that $k \in \mathcal{S}$, so $\exists K \neq U \in \mathbb{L}_\delta(k), U \delta \mathcal{S}$ and by definition (2.6) $k \in U$, hence $k \in U \setminus \{U \in \mathbb{L}_\delta(k) : U \subsetneq K, U \delta \mathcal{S}\}$

The converse of above is not necessary true for example: let $K = \{s, r, c\}$, $T_{\mathbb{L}} = \{\emptyset, K, \{s\}, \{r\}\}$, $\mathbb{L} = \{K, \{s\}, \{r\}, \{s, r\}, \{s, c\}, \{r, c\}\}$, $\mathbb{L}_\delta(r) = \{\{r\}, \{s, r\}, \{r, c\}, K\}$, δ is proximity define by: $\mathcal{S} \delta R \forall \mathcal{S} \neq \emptyset, R \neq \emptyset$ except the relation $:\{r\} \bar{\delta} \{s, c\}, \{s, c\} \bar{\delta} \{r\}, \{s\} \bar{\delta} \{r\}, \{r\} \bar{\delta} \{s\}, \{r\} \bar{\delta} \{c\}, \{c\} \bar{\delta} \{r\}, \mathcal{S} = \{r\}, N_{\mathbb{L}_\delta}(\mathcal{S}) = \{\{r\}, \{s, r\}, \{r, c\}\}$, $\{r\} \cup \{s, r\} \cup \{r, c\} = K \not\subseteq N_{\mathbb{L}_\delta}(\mathcal{S})$.

Remark 3.4: Let $(K_{\mathbb{L}}^{T_{\mathbb{L}}}, \delta)$ be a $\mathbb{L}$ -topological proximity space, then we have the following features of $\mathbb{L}$ -focal nested set:

1. $N_{\mathbb{L}_\delta}(\mathcal{S})$ is not necessary $\mathbb{L}$ -clopen set in general, By above example, $\mathbb{L}_\delta(\mathcal{S}) = \{\{s\}, \{s, r\}, \{r, c\}, K\}, \mathcal{S} = \{r\}, N_{\mathbb{L}_\delta}(\mathcal{S}) = \{s, r\} \notin T_{\mathbb{L}}$ and not $\mathbb{L}$ -closed set.
2. It is not necessary that $N_{\mathbb{L}_\delta}(\mathcal{S}) \subset \mathcal{S}$ in general, for example: let $K = \{s, r, c\}$, $T_{\mathbb{L}} = \{\emptyset, K, \{s\}, \{c\}, \{s, c\}\}$, $\mathbb{L} = \{K, \{s\}, \{c\}, \{s, r\}, \{s, c\}, \{r, c\}\}$, $\mathbb{L}_\delta(r) = \{\{s, c\}, K\}$, δ is proximity define by: $\mathcal{S} \delta R \forall \mathcal{S} \neq \emptyset, R \neq \emptyset$ except the relation $:\{s\} \bar{\delta} \{r, c\}, \{r, c\} \bar{\delta} \{s\}, \{s\} \bar{\delta} \{r\}, \{r\} \bar{\delta} \{s\}, \{s\} \bar{\delta} \{c\}, \{c\} \bar{\delta} \{s\}, \mathcal{S} = \{s\}, N_{\mathbb{L}_\delta}(\mathcal{S}) = \{s, c\} \not\subseteq \mathcal{S}$
3. If $\mathcal{S} = N_{\mathbb{L}_\delta}(\mathcal{S})$ is not necessary $\mathcal{S} \in T_{\mathbb{L}}$, By example in note 3.3 $\mathbb{L}_\delta(c) = \{\{s, r\}, K\}, \mathcal{S} = \{s, r\}, N_{\mathbb{L}_\delta}(\mathcal{S}) = \{s, r\} = \mathcal{S}$ but $\mathcal{S} \notin T_{\mathbb{L}}$

Proposition 3.5: Let $(K_{\mathbb{L}}^{T_{\mathbb{L}}}, \delta)$ be a $\mathbb{L}$ -topological proximity space such that $\mathcal{S}, R \subseteq K$, then each of the following are holds:

1. If $\mathcal{S} \subseteq R$ then $N_{\mathbb{L}_\delta}(\mathcal{S}) \subseteq N_{\mathbb{L}_\delta}(R)$.
2. $N_{\mathbb{L}_\delta}(\mathcal{S} \cap R) \subseteq N_{\mathbb{L}_\delta}(\mathcal{S}) \cap N_{\mathbb{L}_\delta}(R)$.
3. $N_{\mathbb{L}_\delta}(\mathcal{S} \cup R) = N_{\mathbb{L}_\delta}(\mathcal{S}) \cup N_{\mathbb{L}_\delta}(R)$.
4. $N_{\mathbb{L}_\delta}(\mathcal{S}) \subseteq N_{\mathbb{L}_\delta}(N_{\mathbb{L}_\delta}(\mathcal{S}))$.
5. $N_{\mathbb{L}_\delta}(\emptyset) = \emptyset$
6. If $\emptyset \neq \mathcal{S} \in T_{\mathbb{L}}(k)$, then $\mathcal{S} \subseteq N_{\mathbb{L}_\delta}(\mathcal{S})$.

Proof:

1. Let $k \in N_{\mathbb{L}_\delta}(\mathcal{S})$, so there exist $U \in \mathbb{L}_\delta(k), U \delta \mathcal{S}$ but $\mathcal{S} \subseteq R$, then by proposition (2.7 part 2) $U \delta R$, hence $k \in N_{\mathbb{L}_\delta}(R)$.

2. Since $S \cap R \subseteq S$, by (1) $N_{\mathbb{L}_S}(\mathbb{L}_S(S \cap R)) \subseteq N_{\mathbb{L}_S}(\mathbb{L}_S(S))$ and $S \cap R \subseteq R$, by (1) $N_{\mathbb{L}_S}(\mathbb{L}_S(S \cap R)) \subseteq N_{\mathbb{L}_S}(\mathbb{L}_S(R))$ then, $N_{\mathbb{L}_S}(\mathbb{L}_S(S \cap R)) \subseteq N_{\mathbb{L}_S}(\mathbb{L}_S(S)) \cap N_{\mathbb{L}_S}(\mathbb{L}_S(R))$.
3. Since $S \subseteq S \cup R$, by (1) $N_{\mathbb{L}_S}(\mathbb{L}_S(S)) \subseteq N_{\mathbb{L}_S}(\mathbb{L}_S(S \cup R))$ and $R \subseteq S \cup R$, by (1) $N_{\mathbb{L}_S}(\mathbb{L}_S(R)) \subseteq N_{\mathbb{L}_S}(\mathbb{L}_S(S \cup R))$ then, $N_{\mathbb{L}_S}(\mathbb{L}_S(S)) \cup N_{\mathbb{L}_S}(\mathbb{L}_S(R)) \subseteq N_{\mathbb{L}_S}(\mathbb{L}_S(S \cup R))$. Conversely, let $k \in N_{\mathbb{L}_S}(\mathbb{L}_S(S \cup R))$, then there exist $U \in \mathbb{L}_S(k)$, $k \in U$ such that $U \delta S \cup R$, hence by definition (2.6 part (2)) we have $U \delta S$ or $U \delta R$ and from that we get $k \in N_{\mathbb{L}_S}(\mathbb{L}_S(S)) \cup N_{\mathbb{L}_S}(\mathbb{L}_S(R))$.
4. Let $k \in N_{\mathbb{L}_S}(\mathbb{L}_S(S))$, if possible that $k \notin N_{\mathbb{L}_S}(\mathbb{L}_S(N_{\mathbb{L}_S}(\mathbb{L}_S(S))))$, then for each $U \in \mathbb{L}_S(k)$, $U \delta N_{\mathbb{L}_S}(\mathbb{L}_S(S))$ but $k \in U$, $k \delta N_{\mathbb{L}_S}(\mathbb{L}_S(S))$, $k \notin N_{\mathbb{L}_S}(\mathbb{L}_S(S))$ which is a contradiction, thus $k \in N(N_{\mathbb{L}_S}(\mathbb{L}_S(S)))$.
5. If not, $\exists k \in N_{\mathbb{L}_S}(\emptyset)$, then there exist $U \in \mathbb{L}_S(k)$ such that $U \delta \emptyset$ this contradiction $N_{\mathbb{L}_S}(\emptyset) = \emptyset$.
6. If $S = \emptyset$ & $N_{\mathbb{L}_S}(\emptyset) = \emptyset$ so $\emptyset = S \subseteq N_{\mathbb{L}_S}(\emptyset) = \emptyset$. If $S \neq \emptyset$, so $\exists k \in S$, but $S \delta S$ and $S \in T_{\mathbb{L}}(k)$, so $k \in N_{\mathbb{L}_S}(\mathbb{L}_S(S))$.

The converse of (1) is not necessary true for example: let $K = \{s, r, c\}$, $T_{\mathbb{L}} = \{\emptyset, K, \{s\}, \{r\}\}$, $\mathbb{L} = \{K, \{s\}, \{r\}, \{s, r\}, \{s, c\}, \{r, c\}\}$, $\mathbb{L}_S(r) = \{\{r\}, \{s, r\}, \{r, c\}, K\}$, δ is proximity define by: $S \delta R \forall S \neq \emptyset, R \neq \emptyset$ except the relation $:\{c\} \bar{\delta} \{s, r\}, \{s, r\} \bar{\delta} \{c\}, \{c\} \bar{\delta} \{r\}, \{r\} \bar{\delta} \{c\}, \{s\} \bar{\delta} \{c\}, \{c\} \bar{\delta} \{s\} S = \{r\}$, $R = \{c\}$, $N_{\mathbb{L}_S}(\mathbb{L}_S(S)) = \{\{r\}, \{s, r\}, \{s, c\}\}$, $N_{\mathbb{L}_S}(\mathbb{L}_S(R)) = \{s, c\}$, $N_{\mathbb{L}_S}(\mathbb{L}_S(R)) \subseteq N_{\mathbb{L}_S}(\mathbb{L}_S(S))$ but $R \not\subseteq S$.

Also the converse of (2) is not necessary true because By example 2.10, δ is proximity define by: $S \delta R \forall S \neq \emptyset, R \neq \emptyset$ except the relation $:\{r\} \bar{\delta} \{s, c\}, \{s, c\} \bar{\delta} \{r\}, \{s\} \bar{\delta} \{r\}, \{r\} \bar{\delta} \{s\}, \{r\} \bar{\delta} \{c\}, \{c\} \bar{\delta} \{r\}$, $S = \{s, r\}$, $R = \{r, c\}$, $S \cap R = \{r\}$, $N_{\mathbb{L}_S}(\mathbb{L}_S(S)) = N_{\mathbb{L}_S}(\mathbb{L}_S(R)) = \{\{s\}, \{s, r\}, \{s, c\}\} = N_{\mathbb{L}_S}(\mathbb{L}_S(S)) \cap N_{T_{\mathbb{L}}}(\mathbb{L}_S(R))$, $N_{\mathbb{L}_S}(\mathbb{L}_S(S \cap R)) = \{s, r\} \subseteq N_{\mathbb{L}_S}(\mathbb{L}_S(S)) \cap N_{\mathbb{L}_S}(\mathbb{L}_S(R))$ but $N_{\mathbb{L}_S}(\mathbb{L}_S(S)) \cap N_{\mathbb{L}_S}(\mathbb{L}_S(R)) \not\subseteq N_{\mathbb{L}_S}(\mathbb{L}_S(S \cap R))$.

The converse of (4) is not necessary true because by above example, $S = \{r\}$, $N_{\mathbb{L}_S}(\mathbb{L}_S(S)) = \{s, r\}$, $N_{\mathbb{L}_S}(\mathbb{L}_S(N_{\mathbb{L}_S}(\mathbb{L}_S(S)))) = \{\{s\}, \{s, r\}, \{s, c\}\}$ and $N_{\mathbb{L}_S}(\mathbb{L}_S(N_{\mathbb{L}_S}(\mathbb{L}_S(S)))) \not\subseteq N_{\mathbb{L}_S}(\mathbb{L}_S(S))$.

Corollary 3.6: Let $(K_{\mathbb{L}}^{T_{\mathbb{L}}}, \delta)$ be advance $\mathbb{L}$ – topological proximity space, then $N_{\mathbb{L}_S}(\mathbb{L}_S(S \cap R)) = N_{\mathbb{L}_S}(\mathbb{L}_S(S)) \cap N_{\mathbb{L}_S}(\mathbb{L}_S(R))$.

Proposition 3.7: Let $(K_{\mathbb{L}_i}^{T_{\mathbb{L}_i}}, \delta)$ $i = 1, 2$ be a $\mathbb{L}$ – topological proximity space, if $\mathbb{L}_2$ is finer than $\mathbb{L}_1$ then $N_{\mathbb{L}_1 S}(\mathbb{L}_1(S)) \subseteq N_{\mathbb{L}_2 S}(\mathbb{L}_2(S))$ for each S of K .

Proof: Let $k \in N_{\mathbb{I}_1\delta}(\mathcal{S})$ so there exist $U \in \mathbb{I}_1\delta(k)$ such that $U \delta \mathcal{S}$, by proposition (2.13) $U \in \mathbb{I}_2\delta(k)$ and $U \delta \mathcal{S}$ so $k \in N_{\mathbb{I}_2\delta}(\mathcal{S})$.

Proposition 3.8: In $\mathbb{I}$ -topological proximity space $(K_{\mathbb{I}}^{T_{\mathbb{I}}}, \delta)$, $N_{\mathbb{I}\delta}(\mathcal{S}) \neq \emptyset$ for each $\mathbb{I}$ -focal proper subset $\mathcal{S}$ of K .

Proof: Let $\mathcal{S}$ is a $\mathbb{I}$ -focal proper subset of K . Then $\mathcal{S} \in \mathbb{I}\delta(k)$, that is, $\mathcal{S} \delta \mathcal{S}$, thus $\mathcal{S} \in N_{\mathbb{I}\delta}(\mathcal{S})$, hence $N_{\mathbb{I}\delta}(\mathcal{S}) \neq \emptyset$.

Proposition 3.9: Let $(K_{\mathbb{I}}^{T_{\mathbb{I}}}, \delta)$ be a $\mathbb{I}$ -topological proximity space and $\mathcal{S} \in T_{\mathbb{I}}(K) \forall k \in K$ then:

1. $U \cap N_{T_{\mathbb{I}}}(\mathcal{S}) \subseteq N_{T_{\mathbb{I}}}(\mathcal{S} \cap U)$.
2. $U \cap N_{T_{\mathbb{I}}}(\mathcal{S}) \subseteq N_{\mathbb{I}\delta}(\mathcal{S} \cap U)$.

Proof:

1. Let $r \in U \cap N_{T_{\mathbb{I}}}(\mathcal{S}) \Rightarrow r \in U$ and $r \in N_{T_{\mathbb{I}}}(\mathcal{S}), \exists H \in T_{\mathbb{I}}(r), H \delta \mathcal{S}$. By proposition 2.14 part 5, $N_{T_{\mathbb{I}}}(\mathcal{S}) \subseteq \mathcal{S}$, then $r \in \mathcal{S}$, that is, $r \in (H \cap U \cap \mathcal{S})$. By Definition 2.6 part 4, $H \delta U \cap \mathcal{S}$ thus $r \in N_{T_{\mathbb{I}}}(\mathcal{S} \cap U)$.
2. by (1) $U \cap N_{T_{\mathbb{I}}}(\mathcal{S}) \subseteq N_{T_{\mathbb{I}}}(\mathcal{S} \cap U)$ and by proposition 3.3 $N_{T_{\mathbb{I}}}(\mathcal{S} \cap U) \subseteq N_{\mathbb{I}\delta}(\mathcal{S} \cap U)$, $U \cap N_{T_{\mathbb{I}}}(\mathcal{S}) \subseteq N_{\mathbb{I}\delta}(\mathcal{S} \cap U)$.

4. $\mathbb{I}$ -Focal ingrained set

Definition 4.1: Let $(K_{\mathbb{I}}^{T_{\mathbb{I}}}, \delta)$ be a $\mathbb{I}$ -topological proximity space then a point $k \in K$ is called a $\mathbb{I}$ -focal ingrained point of $\mathcal{S} \subseteq K$ if and only if for each $U \in \mathbb{I}\delta(k)$ is a proper subset of $K, k \in U$ such that $U \bar{\delta} K - \mathcal{S}$. The set of all $\mathbb{I}$ -focal ingrained points of a set $\mathcal{S}$ is called a $\mathbb{I}$ -focal ingrained set and denoted by $C_{\mathbb{I}\delta}(\mathcal{S})$, i.e. $C_{\mathbb{I}\delta}(\mathcal{S}) = \{k \in K : \exists U \in \mathbb{I}\delta(k), U \bar{\delta} K \setminus \mathcal{S}\}$ where $\mathbb{I}\delta(k) = \{U \in \mathbb{I}\delta(k), k \in U\}$.

By example 2.11, δ is a proximity define by: $\mathcal{S} \delta R \forall \mathcal{S} \neq \emptyset, R \neq \emptyset$ except the relation: $\{\mathcal{S}\} \bar{\delta} \{r, \mathcal{C}\}, \{r, \mathcal{C}\} \bar{\delta} \{\mathcal{S}\}, \{\mathcal{S}\} \bar{\delta} \{r\}, \{r\} \bar{\delta} \{\mathcal{S}\}, \{\mathcal{S}\} \bar{\delta} \{\mathcal{C}\}, \{\mathcal{C}\} \bar{\delta} \{\mathcal{S}\}, \mathcal{S} = \{\mathcal{S}\}, K \setminus \mathcal{S} = \{r, \mathcal{C}\}, C_{\mathbb{I}\delta}(\mathcal{S}) = \{\mathcal{S}\}$.

Remark 4.2:

1. $K \setminus N_{\mathbb{I}\delta}(K \setminus \mathcal{S}) = C_{\mathbb{I}\delta}(\mathcal{S})$
2. $N_{\mathbb{I}\delta}(K \setminus \mathcal{S}) = K \setminus C_{\mathbb{I}\delta}(\mathcal{S})$.
3. $K \setminus C_{\mathbb{I}\delta}(K \setminus \mathcal{S}) = N_{\mathbb{I}\delta}(\mathcal{S})$

Proof:

1. $k \in K \setminus N_{\mathbb{L}_\phi}(K \setminus S)$ if and only if $k \notin N_{\mathbb{L}_\phi}(K \setminus S)$ if and only if $\forall K \neq U \in \mathbb{L}_\phi(k)$ such that $U \bar{\delta} K \setminus S$ if and only if $k \in C_{\mathbb{L}_\phi}(S)$.
2. $k \in N_{T_\mathbb{L}}(K \setminus S)$ if and only if $k \notin K \setminus N_{\mathbb{L}_\phi}(K \setminus S) = C_{\mathbb{L}_\phi}(S)$ by above 1 $k \notin C_{\mathbb{L}_\phi}(S)$ if and only if $k \in K \setminus C_{\mathbb{L}_\phi}(S)$.
3. $k \in K \setminus C_{\mathbb{L}_\phi}(K \setminus S)$ if and only if $k \notin C_{\mathbb{L}_\phi}(K \setminus S)$ if and only if $\exists K \neq U \in \mathbb{L}_\phi(k)$ such that $U \delta K(K \setminus S) = S$ if and only if $k \in N_{\mathbb{L}_\phi}(S)$.

Proposition 4.3: Let $(K_\mathbb{L}^{T_\mathbb{L}}, \delta)$ be a $\mathbb{L}$ -topological proximity space, then $C_{\mathbb{L}_\phi}(S) \subseteq C_{T_\mathbb{L}}(S)$ for each subset S of X .

Proof: $k \in C_{\mathbb{L}_\phi}(S)$ if and only if $k \in K \setminus N_{\mathbb{L}_\phi}(K \setminus S)$ if and only if $k \notin N_{\mathbb{L}_\phi}(K \setminus S)$ by proposition (3.3) $k \notin N_{T_\mathbb{L}}(K \setminus S)$ then $k \in K \setminus N_{T_\mathbb{L}}(K \setminus S)$ then $k \in C_{T_\mathbb{L}}(S)$.

The converse of above proposition is not necessary true by example, let $K = \{s, r, c\}$, $T_\mathbb{L} = \{\emptyset, K, \{s\}, \{c\}, \{s, c\}\}$, $\mathbb{L} = \{K, \{s\}, \{c\}, \{s, r\}, \{s, c\}, \{r, c\}\}$, $\mathbb{L}_\phi(S) = \{\{s\}, \{s, r\}, \{s, c\}, K\}$, δ is proximity define by: $S \delta R \forall S \neq \emptyset, R \neq \emptyset$ except the relation : $\{r\} \bar{\delta} \{s, c\}, \{s, c\} \bar{\delta} \{r\}, \{s\} \bar{\delta} \{r\}, \{r\} \bar{\delta} \{s\}, \{r\} \bar{\delta} \{c\}, \{c\} \bar{\delta} \{r\}$, $S = \{s, c\}$, $K \setminus S = \{r\}$, $C_{\mathbb{L}_\phi}(S) = \{\{s\}, \{s, c\}\}$, $C_{T_\mathbb{L}}(S) = \{\{s\}, \{c\}, \{s, c\}\}$, $C_{\mathbb{L}_\phi}(S) \subseteq C_{T_\mathbb{L}}(S)$ but $C_{T_\mathbb{L}}(S) \not\subseteq C_{\mathbb{L}_\phi}(S)$.

Note 4.4: Let $(K_\mathbb{L}^{T_\mathbb{L}}, \delta)$ be a $\mathbb{L}$ -topological proximity space, then $C_{\mathbb{L}_\phi}(S) \subseteq \cup \{U \in \mathbb{L}_\phi(k), U \bar{\delta} K \setminus S, k \in S\}$.

Proof: Let $k \in C_{\mathbb{L}_\phi}(S)$, $\forall K \neq U \in \mathbb{L}_\phi(k)$ such that $U \bar{\delta} K \setminus S$, $U \cap K \setminus S = \emptyset \Rightarrow U \subseteq S$ but $k \in U$ hence, $k \in \cup \{U \in \mathbb{L}_\phi(k), U \bar{\delta} K \setminus S, k \in S\}$.

Remark 4.5:

1. $C_{\mathbb{L}_\phi}(S)$ is not necessary $\mathbb{L}$ -clopen set in general. By example in definition 4.1 $C_{\mathbb{L}_\phi}(S) = \{s\} \notin T_\mathbb{L}$ and not $\mathbb{L}$ -closed set.
2. It is not necessary that $C_{\mathbb{L}_\phi}(S) \subseteq S$ in general. By example in proposition 4.3 $C_{\mathbb{L}_\phi}(S) \not\subseteq S$.
3. If $S = C_{\mathbb{L}_\phi}(S)$ is not necessary $S \in T_\mathbb{L}$. For example, let $K = \{s, r, c\}$, $T_\mathbb{L} = \{\emptyset, K, \{s\}, \{r\}\}$, $\mathbb{L} = \{K, \{s\}, \{r\}, \{s, r\}, \{s, c\}, \{r, c\}\}$, $\mathbb{L}_\phi(c) = \{\{s, r\}, K\}$, δ is proximity define by: $S \delta R \forall S \neq \emptyset, R \neq \emptyset$ except the relation : $\{c\} \bar{\delta} \{s, r\}, \{s, r\} \bar{\delta} \{c\}, \{c\} \bar{\delta} \{r\}, \{r\} \bar{\delta} \{c\}, \{s\} \bar{\delta} \{c\}, \{c\} \bar{\delta} \{s\}$, $S = \{s, r\}$, $K \setminus S = \{c\}$, $C_{\mathbb{L}_\phi}(S) = \{s, r\} = S$ but $S \notin T_\mathbb{L}$.

Proposition 4.6: Let $(K_b^{T_b}, \delta)$ be a $\mathbb{J}$ -topological proximity space such that $\mathbb{S}, \mathbb{R} \subseteq K$, then the following are holds:

1. If $\mathbb{S} \subseteq \mathbb{R}$ then $C_{\mathbb{J}_b}(\mathbb{S}) \subseteq C_{\mathbb{J}_b}(\mathbb{R})$.
2. $C_{\mathbb{J}_b}(\mathbb{S} \cap \mathbb{R}) = C_{\mathbb{J}_b}(\mathbb{S}) \cap C_{\mathbb{J}_b}(\mathbb{R})$.
3. If $(K_b^{T_b}, \delta)$ be advance, then $C_{\mathbb{J}_b}(\mathbb{S} \cup \mathbb{R}) = C_{\mathbb{J}_b}(\mathbb{S}) \cup C_{\mathbb{J}_b}(\mathbb{R})$.
4. $C_{\mathbb{J}_b}(C_{\mathbb{J}_b}(\mathbb{S})) \subseteq C_{\mathbb{J}_b}(\mathbb{S})$.
5. $C_{\mathbb{J}_b}(\emptyset) = \emptyset$
6. If $\emptyset \neq \mathbb{S} \in T_b(k)$, then $C_{\mathbb{J}_b}(K \setminus \mathbb{S}) \subseteq K \setminus \mathbb{S}$.

Proof:

1. $\mathbb{S} \subseteq \mathbb{R}$ if and only if $K \setminus \mathbb{R} \subseteq K \setminus \mathbb{S}$ by proposition(3.5 part 1) $N_{\mathbb{J}_b}(K \setminus \mathbb{R}) \subseteq N_{\mathbb{J}_b}(K \setminus \mathbb{S})$ if and only if $K \setminus N_{\mathbb{J}_b}(K \setminus \mathbb{S}) \subseteq K \setminus N_{\mathbb{J}_b}(K \setminus \mathbb{R})$ if and only if $C_{\mathbb{J}_b}(\mathbb{S}) \subseteq C_{\mathbb{J}_b}(\mathbb{R})$.
2. $k \in C_{\mathbb{J}_b}(\mathbb{S} \cap \mathbb{R})$ if and only if $k \in K \setminus N_{\mathbb{J}_b}(K \setminus \mathbb{S} \cap \mathbb{R})$ if and only if $k \notin N_{\mathbb{J}_b}(K \setminus \mathbb{S} \cap \mathbb{R})$ if and only if $k \notin N_{\mathbb{J}_b}(K \setminus \mathbb{S} \cup K \setminus \mathbb{R})$, by proposition(3.5 part 3) $k \notin ((N_{\mathbb{J}_b}(K \setminus \mathbb{S}) \cup N_{\mathbb{J}_b}(K \setminus \mathbb{R}))$ if and only if $k \notin N_{\mathbb{J}_b}(K \setminus \mathbb{S})$ and $k \notin N_{\mathbb{J}_b}(K \setminus \mathbb{R})$ if and only if $k \in K \setminus N_{\mathbb{J}_b}(K \setminus \mathbb{S})$ and $k \in K \setminus N_{\mathbb{J}_b}(K \setminus \mathbb{R})$ if and only if $k \in C_{\mathbb{J}_b}(\mathbb{S})$ and $k \in C_{\mathbb{J}_b}(\mathbb{R})$ if and only if $k \in (C_{\mathbb{J}_b}(\mathbb{S}) \cap C_{\mathbb{J}_b}(\mathbb{R}))$.
3. Since $\mathbb{S} \subseteq \mathbb{S} \cup \mathbb{R}$ so by 1 $C_{\mathbb{J}_b}(\mathbb{S}) \subseteq C_{\mathbb{J}_b}(\mathbb{S} \cup \mathbb{R})$ and $\mathbb{R} \subseteq \mathbb{S} \cup \mathbb{R}$ so by 1 $C_{\mathbb{J}_b}(\mathbb{R}) \subseteq C_{\mathbb{J}_b}(\mathbb{S} \cup \mathbb{R})$ we get that $C_{\mathbb{J}_b}(\mathbb{S}) \cup C_{\mathbb{J}_b}(\mathbb{R}) \subseteq C_{\mathbb{J}_b}(\mathbb{S} \cup \mathbb{R})$. Conversely, let $k \in C_{\mathbb{J}_b}(\mathbb{S} \cup \mathbb{R})$ if and only if $k \in K \setminus N_{\mathbb{J}_b}(K \setminus \mathbb{S} \cup \mathbb{R})$ if and only if $k \notin N_{\mathbb{J}_b}(K \setminus \mathbb{S} \cup \mathbb{R})$ if and only if $k \notin N_{\mathbb{J}_b}(K \setminus \mathbb{S} \cap K \setminus \mathbb{R})$, by corollary (3.6) $k \notin ((N_{\mathbb{J}_b}(K \setminus \mathbb{S}) \cap N_{\mathbb{J}_b}(K \setminus \mathbb{R}))$ if and only if $k \notin N_{\mathbb{J}_b}(K \setminus \mathbb{S})$ or $k \notin N_{\mathbb{J}_b}(K \setminus \mathbb{R})$ if and only if $k \in K \setminus N_{\mathbb{J}_b}(K \setminus \mathbb{S})$ or $k \in K \setminus N_{\mathbb{J}_b}(K \setminus \mathbb{R})$ if and only if $k \in C_{\mathbb{J}_b}(\mathbb{S})$ or $k \in C_{\mathbb{J}_b}(\mathbb{R})$ if and only if $k \in (C_{\mathbb{J}_b}(\mathbb{S}) \cup C_{\mathbb{J}_b}(\mathbb{R}))$.
4. $k \in C_{\mathbb{J}_b}(C_{\mathbb{J}_b}(\mathbb{S}))$ if and only if $k \in K \setminus N_{\mathbb{J}_b}(K \setminus C_{\mathbb{J}_b}(\mathbb{S}))$ if and only if $k \in K \setminus N_{\mathbb{J}_b}(K \setminus K \setminus N_{\mathbb{J}_b}(K \setminus \mathbb{S}))$, if and only if $k \in K \setminus N_{\mathbb{J}_b}(N_{\mathbb{J}_b}(K \setminus \mathbb{S}))$ $k \notin N_{\mathbb{J}_b}(N_{\mathbb{J}_b}(K \setminus \mathbb{S}))$, by proposition (3.5 part 4) then $k \notin N_{\mathbb{J}_b}(K \setminus \mathbb{S})$, $k \in K \setminus N_{\mathbb{J}_b}(K \setminus \mathbb{S}) = C_{\mathbb{J}_b}(\mathbb{S})$
5. If not, $\exists k \in C_{\mathbb{J}_b}(\emptyset)$, then there exist $U \in \mathbb{J}_b(k)$ such that $U \bar{\delta} K \setminus \emptyset = K$ this contradiction $C_{\mathbb{J}_b}(\emptyset) = \emptyset$
6. $\mathbb{S} \in T_b(k)$, by proposition (3.5 part 6), $\mathbb{S} \subseteq N_{\mathbb{J}_b}(\mathbb{S})$, $\mathbb{S} \subseteq K \setminus C_{\mathbb{J}_b}(K \setminus \mathbb{S})$, $C_{\mathbb{J}_b}(K \setminus \mathbb{S}) \subseteq K \setminus \mathbb{S}$.

Corollary 4.7: If $\mathcal{S}$ is $\mathbb{J}$ – closed then $\mathcal{C}_{\mathbb{J}\mathcal{S}}(\mathcal{S}) \subseteq \mathcal{S}$.

Proof: $k \in \mathcal{S}, k \notin \mathcal{K} \setminus \mathcal{S}, \mathcal{K} \setminus \mathcal{S} \in \mathbb{T}_{\mathbb{J}}(k), \mathcal{K} \setminus \mathcal{S} \subseteq \mathbb{N}_{\mathbb{J}\mathcal{S}}(\mathcal{K} \setminus \mathcal{S})$ by proposition (3.6 part6), $\mathcal{K} \setminus \mathbb{N}_{\mathbb{J}\mathcal{S}}(\mathcal{K} \setminus \mathcal{S}) \subseteq \mathcal{K} \setminus (\mathcal{K} \setminus \mathcal{S}) = \mathcal{S}, \mathcal{C}_{\mathbb{J}\mathcal{S}}(\mathcal{S}) \subseteq \mathcal{S}$.

Proposition 4.8: Let $(\mathcal{K}_{\mathbb{J}i}^{\mathbb{T}_{\mathbb{J}}}, \delta)$ $i = 1, 2$ be a $\mathbb{J}$ – topological proximity space, if $\mathbb{J}_2$ is finer than $\mathbb{J}_1$ then $\mathcal{C}_{\mathbb{J}_1\mathcal{S}}(\mathcal{S}) \subseteq \mathcal{C}_{\mathbb{J}_2\mathcal{S}}(\mathcal{S})$ for each $\mathcal{S}$ of $\mathcal{K}$.

Proof: Let $k \in \mathcal{C}_{\mathbb{J}_1\mathcal{S}}(\mathcal{S})$ if and only if $k \in \mathcal{K} \setminus \mathbb{N}_{\mathbb{J}_2\mathcal{S}}(\mathcal{K} \setminus \mathcal{S})$ if and only if $k \notin \mathbb{N}_{\mathbb{J}_2\mathcal{S}}(\mathcal{K} \setminus \mathcal{S})$ by proposition (3.9) $k \notin \mathbb{N}_{\mathbb{J}_1\mathcal{S}}(\mathcal{K} \setminus \mathcal{S}), k \in \mathcal{K} \setminus \mathbb{N}_{\mathbb{J}_1\mathcal{S}}(\mathcal{K} \setminus \mathcal{S}) = \mathcal{C}_{\mathbb{J}_1\mathcal{S}}(\mathcal{S})$.

Proposition 4.9: In $\mathbb{J}$ – topological proximity space $(\mathcal{K}_{\mathbb{J}}^{\mathbb{T}_{\mathbb{J}}}, \delta)$, $\mathcal{C}_{\mathbb{J}\mathcal{S}}(\mathcal{S}) = \emptyset$ for each $\mathbb{J}$ – focal proper subset $\mathcal{S}$ of $\mathcal{K}$.

Proof: If possible $\mathcal{C}_{\mathbb{J}\mathcal{S}}(\mathcal{S}) \neq \emptyset$, then $\exists k \in \mathcal{C}_{\mathbb{J}\mathcal{S}}(\mathcal{S})$ and $\forall \mathcal{K} \neq \mathcal{U} \in \mathbb{J}_{\mathcal{S}}(k)$ such that $\mathcal{U} \bar{\delta} \mathcal{K} \setminus \mathcal{S}$ and this means $\mathcal{U} \cap \mathcal{K} \setminus \mathcal{S} = \emptyset$ by proposition (2.12 part 2) $\mathcal{K} \setminus \mathcal{U} \notin \mathbb{J}_{\mathcal{S}}(k)$ and $\mathcal{S} \subset \mathcal{K} \setminus \mathcal{U}$, hence $\mathcal{S} \notin \mathbb{J}_{\mathcal{S}}(k)$ which contradiction because $\mathcal{S}$ is a $\mathbb{J}$ – focal set.

Proposition 4.10: Let $(\mathcal{K}_{\mathbb{J}}^{\mathbb{T}_{\mathbb{J}}}, \delta)$ be a $\mathbb{J}$ – topological proximity space and $\mathcal{S} \in \mathbb{T}_{\mathbb{J}}(k)$ then:

1. $\mathcal{U} \cap \mathcal{K} \setminus \mathcal{C}_{\mathbb{T}_{\mathbb{J}}}(\mathcal{K} \setminus \mathcal{S}) \subseteq \mathcal{K} \setminus \mathcal{C}_{\mathbb{T}_{\mathbb{J}}}(\mathcal{K} \setminus \mathcal{S} \cap \mathcal{U})$.
2. $\mathcal{U} \cap \mathcal{K} \setminus \mathcal{C}_{\mathbb{T}_{\mathbb{J}}}(\mathcal{K} \setminus \mathcal{S}) \subseteq \mathcal{K} \setminus \mathcal{C}_{\mathbb{J}\mathcal{S}}(\mathcal{K} \setminus \mathcal{S} \cap \mathcal{U}), \mathcal{C}_{\mathbb{T}_{\mathbb{J}}}(\mathcal{S}) = \{k \in \mathcal{K} : \forall \mathcal{K} \neq \mathcal{U} \in \mathbb{T}_{\mathbb{J}}(k), \mathcal{U} \bar{\delta} \mathcal{K} \setminus \mathcal{S}\}$.

Proof:

1. Let $r \in \mathcal{U} \cap \mathcal{K} \setminus \mathcal{C}_{\mathbb{T}_{\mathbb{J}}}(\mathcal{K} \setminus \mathcal{S}) \Rightarrow r \in \mathcal{U}$ and $r \in \mathcal{K} \setminus \mathcal{C}_{\mathbb{T}_{\mathbb{J}}}(\mathcal{K} \setminus \mathcal{S})$, thus $r \notin \mathcal{C}_{\mathbb{T}_{\mathbb{J}}}(\mathcal{K} \setminus \mathcal{S}), \exists \mathcal{K} \neq \mathcal{U} \in \mathbb{T}_{\mathbb{J}}(k)$ such that $\mathcal{U} \bar{\delta} \mathcal{K} \setminus \mathcal{S}$. By proposition 2.7 part 1, $\mathcal{U} \bar{\delta} (\mathcal{K} \setminus \mathcal{S} \cap \mathcal{U})$, that is, $r \notin \mathcal{C}_{\mathbb{T}_{\mathbb{J}}}(\mathcal{K} \setminus \mathcal{S} \cap \mathcal{U})$, thus $r \in \mathcal{U} \cap \mathcal{K} \setminus \mathcal{C}_{\mathbb{T}_{\mathbb{J}}}(\mathcal{K} \setminus \mathcal{S} \cap \mathcal{U})$.
2. By part (1) $\mathcal{U} \cap \mathcal{K} \setminus \mathcal{C}_{\mathbb{T}_{\mathbb{J}}}(\mathcal{K} \setminus \mathcal{S}) \subseteq \mathcal{K} \setminus \mathcal{C}_{\mathbb{T}_{\mathbb{J}}}(\mathcal{K} \setminus \mathcal{S} \cap \mathcal{U})$ and by proposition (3.3) $\mathcal{K} \setminus \mathcal{C}_{\mathbb{T}_{\mathbb{J}}}(\mathcal{K} \setminus \mathcal{S} \cap \mathcal{U}) \subseteq \mathcal{K} \setminus \mathcal{C}_{\mathbb{J}\mathcal{S}}(\mathcal{K} \setminus \mathcal{S} \cap \mathcal{U}), \mathcal{U} \cap \mathcal{K} \setminus \mathcal{C}_{\mathbb{T}_{\mathbb{J}}}(\mathcal{K} \setminus \mathcal{S}) \subseteq \mathcal{K} \setminus \mathcal{C}_{\mathbb{J}\mathcal{S}}(\mathcal{K} \setminus \mathcal{S} \cap \mathcal{U})$.

5. Conclusion

The researchers concluded in this study that it is possible to connect the $\mathbb{J}$ – Focal set concept with the $\mathbb{J}$ – Nested set concept based on proximity space, thus finding new concepts similar to the previous ones. The $\mathbb{J}$ – Focal Nested set contains the $\mathbb{J}$ – Nested set, and the $\mathbb{J}$ – Focal nested set does not necessarily have

to be an $\mathbb{F}$ –open or $\mathbb{F}$ –closed set, as explained in Note 3.5 (1). Additionally, a complement can be found to define the $\mathbb{F}$ –Focal Nested set, which can be observed in Note 4.2.

References

- [1] F. Riesz, *Sur les opérations fonctionnelles linéaires*. Paris: Gauthier-Villars (1909).
- [2] K. Kuratowski, *Topologie I*. Warszawa: Polska Akademia Nauk (1933).
- [3] Y. K. Al Talkany and L. A. Al Swidi, “Focal function in i-topological spaces via proximity spaces,” *J. Phys. Conf. Ser.*, vol. 1 (2020).
- [4] K. Hasan and L. Al-Swidi, “Focal frontier operator in I-topological proximity spaces,” in *AIP Conf. Proc.*, vol. 2839, no. 1 (2023).
- [5] S. M. Kadham and A. N. Alkiffai, “Model tumor response to cancer treatment using fuzzy partial SH-transform: An analytic study,” *Int. J. Math. Comput. Sci.*, vol. 18, pp. 23–28 (2022).
- [6] G. Choquet, “Sur les notions de filter et grill,” *C. R. Acad. Sci. Paris*, vol. 224, pp. 171–173 (1947).
- [7] M. A. Mustafa, S. M. Kadham, N. K. Abbass, S. Karupusamy, H. Y. Jasim, B. A. Alreda, Z. I. Al Mashhadani, W. R. Abd AL-Hussein, and M. T. Ahmed, “A novel fuzzy M-transform technique for sustainable ground water level prediction,” *Appl. Geomat.*, vol. 16, no. 1, pp. 9–15 (2024).
- [8] M. M. Abbood, H. H. Ebrahim, A. Al-Fayadh, and A. J. Obaid, “Measure defined on Γ –algebra and some of their generalizations,” *J. Interdiscip. Math.*, vol. 26, no. 5, pp. 821–827 (2023), doi: 10.47974/JIM-1502.

Received December, 2024