

Solitons on Kenmotsu manifolds

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Abstract

In this article properties of solitons on Kenmotsu manifolds with Da-homothetic deformation and Schouten-van Kampen connection are discussed.

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1. Introduction

Solov'ev studied properties of a hyperdistribution in Riemannian manifold with Schouten-van Kampen connection [2,3,4]. Then Schouten-van Kampen connection are studied by different authers with different structures [5,6,7,8].

Almost Ricci soliton is given as [14].

$$L_A G + 2Ric + 2\delta G = 0, \quad 1.1$$

Almost η -Ricci soliton is given as [15, 21].

$$L_A G + 2Ric + 2\delta G + 2\mu\eta \otimes \eta = 0. \quad 1.2$$

Hamilton [14] defined Yamabe flow to solve Yamabe problem and inesively studies by [16, 17, 18, 19].

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Almost Yamabe soliton is defined as [17],

$$\frac{1}{2}(L_A G) = (scal - \lambda)G. \quad 1.3$$

2. Preliminaries

An almost contact metric structure (J, ζ, η, G) satisfies [10, 12, 13].

$$J^2(A) = -A + \eta(A)\zeta, \eta(\zeta) = 1, J\zeta = 0, \eta J = 0, \quad 2.1$$

$$G(JA, JB) = G(A, B) - \eta(A)\eta(B). \quad 2.2$$

Kenmotsu manifold satisfies [11].

$$(D_A J)B = G(JA, B)\zeta - \eta(B)JA. \quad 2.3$$

In this case,

$$D_A \zeta = A - \eta(A)\zeta \text{ and } (\nabla_A \eta)B = G(JA, B). \quad 2.4$$

Da-homothetic deformation satisfies [9].

$$\eta^a = a\eta, \zeta^a = \frac{1}{a}\zeta, J^a = J, G^a = aG + a(a-1)\eta \otimes \eta, \quad 2.5$$

here $(J^a, \zeta^a, \eta^a, G^a)$ is an almost contact metric structure [7].

$\tilde{\nabla}$ and D are related by [1, 2],

$$\tilde{\nabla}_A B = D_A B - \eta(B)\nabla_A \zeta + (\nabla_A \eta)(B)\zeta. \quad 2.6$$

3. Da-Homothetic deformation

By simple calculation we have,

Lemma 1: For Kenmotsu manifold M , D^a in terms of D is

$$D^a_A B = D_A B + (a-1)\{G(A, B)\zeta - \eta(A)\eta(B)\zeta\}. \quad 3.1$$

By this relation, relation between K^a & K is given by theorem 1 where K^a and K are Riemannian curvature tensors with respect to Da-homothetic deformation and Levi-Civita connection.

Theorem 1: For Kenmotsu manifold M and Da-homothetic deformation on M , the curvature tensor K^a is

$$K^a(A, B)C = K(A, B)C + (a-1)\{2G(B, C)A - 2G(A, C)B + 2\eta(A)\eta(C)B - 2\eta(B)\eta(C)A + G(A, C)\eta(B)\zeta - G(B, C)\eta(A)\zeta\}. \quad 3.2$$

by (3.2) we have,

$$Ric^a(B, C) = Ric(B, C) + 3(a-1)G(B, C) - 3(a-1)\eta(B)\eta(C). \quad 3.3$$

Here Ric^a and Ric are Ricci tensors with respect to D^a and D respectively.

Replacing B and C by $v_i (i=1, 2, 3)$ in (3.3), as v_i is a tangent space orthonormal basis at each point on the manifold, we gives,

$$scal^a = scal + 6(a-1). \quad 3.4$$

Here $scal^a$ and $scal$ are scalar curvature with respect to D^a and D .

Lemma 2: For Kenmotsu manifold M and Da -homothetic deformation on M , and any vector field A, B on M , the connections $\tilde{\nabla}$ and D are

$$\tilde{\nabla}_A B = D_A B \quad 3.5$$

Theorem 2: For Kenmotsu manifold M with $\tilde{\nabla}^a, \tilde{K}^a$ and K are related by

$$\begin{aligned} \tilde{K}^a(A, B)C = & K(A, B)C + (3a-2)\{G(B, C)A - G(A, C)B\} - (a^2 - 3a + 2) \\ & \{\eta(A)\eta(C)B - \eta(B)\eta(C)A\} + G(A, C)\eta(B)\zeta - \eta(B, C)\eta(A)\zeta. \end{aligned} \quad 3.6$$

By (3.6) we have,

$$\widetilde{Ric}^a(B, C) = Ric(B, C) + 2(2a^2 - 3a + 2)\{G(B, C) - \eta(B)\eta(C)\} + (a-1)G(B, C). \quad 3.7$$

The Ricci tensor and scalar curvature are related by [2, 3, 4, 5, 6, 7, 8, 9, 20, 22].

$$Ric(A, B) = \left(\frac{scal}{2} + 1\right)G(A, B) - \left(\frac{scal}{2} + 3\right)\eta(A)\eta(B). \quad 3.8$$

With (3.8), (3.7) becomes,

$$\begin{aligned} \widetilde{Ric}^a(B, C) = & \left\{\frac{scal}{2} + (4a^2 - 6a + 5)\right\}G(B, C) - \left\{\frac{scal}{2} + (2a^2 - 6a + 7)\right\}\eta(C)\eta(B) \\ & + (a-1)G(B, C). \end{aligned} \quad 3.9$$

Replacing B and C by $v_i (i=1, 2, 3)$, in (3.9), as v_i is a tangent space orthonormal basis at each point on the manifold, we gives,

$$\widetilde{scal}^a = scal + (10a^2 - 12a + 8). \quad 3.10$$

4. Solitons

Definition: If Ricci tensor of M is of the form,

$$\widetilde{Ric}^a = \alpha G^a + \beta \eta^a \otimes \eta^a,$$

then manifold is known as η^a -Einstein manifold.

On a Kenmotsu manifold with $\widetilde{\nabla}^a$ equation(1.1) becomes,

$$\widetilde{L}_A G^a + 2\widetilde{Ric}^a + 2\delta G^a(A, B) = 0. \quad 4.1$$

Replacing A by ζ in (4.1) gives,

$$\begin{aligned} G^a(\widetilde{\nabla}_A \zeta^a, B) + G^a(A, \widetilde{\nabla}_B \zeta^a) + G^a(\nabla_A \zeta^a, B) + G^a(A, \nabla_B \zeta^a) \\ + 2\widetilde{Ric}^a(A, B) + 2\delta G^a(A, B) = 0. \end{aligned} \quad 4.2$$

By (2.4), (2.6), (3.1), (3.5) and (3.9), equation(4.2) gives,

$$\begin{aligned} 2(2-a)\{G(A, B) - \eta(A)\eta(B)\} + 2\left[\left\{\frac{scal}{2} + (4a^2 - 6a + 5)\right\}G(A, B) \right. \\ \left. - \left\{\frac{scal}{2} + (2a^2 - 6a + 7)\right\}\eta(A)\eta(B) - (a-1)G(A, B)\right] + 2\delta\{aG(A, B) \\ + a(a-1)\eta(A)\eta(B)\} = 0. \end{aligned} \quad (4.3)$$

Replacing A and B by ζ in (4.3) gives,

$$2(a^2 - 1) + a^2\delta = 0 \text{ i.e. } \delta = \frac{2(1-a^2)}{a^2}.$$

Therefore, we have,

Theorem 3: Kenmotsu manifold with $\widetilde{\nabla}^a$ is (i) Expanding if $1-a^2 > 0$, (ii) shrinking if $1-a^2 < 0$ and (iii) steady if $1-a^2 = 0$.

By (4.3),

$$\widetilde{Ric}^a(A, B) = \left(\frac{a-2}{a} - \delta\right)G^a(A, B) + \frac{2-a}{a}\eta^a(A)\eta^a(B).$$

Therefore we have,

Theorem 4: A Kenmotsu manifold M with $\widetilde{\nabla}^a$ is an η^a -Einstein manifold.

On a Kenmotsu manifold with Da-homothetic deformation and Schouten-van Kampen connection equation (1.2) can be given as,

$$(\widetilde{L}_A G^a + 2\widetilde{Ric}^a + 2\delta G^a + 2\mu\eta^a \otimes \eta^a)(A, B) = 0. \quad 4.4$$

Replacing A by ζ^a in (4.4) and with (2.4), (2.6), (3.1), (3.5), and (3.9), we have

$$\widetilde{Ric}^a(A, B) = \left(\frac{a-2}{a} - \delta\right)g^a(A, B) - \left(\frac{a-2}{a} + \mu\right)\eta^a(A)\eta^a(B). \quad 4.5$$

Therefore,

Theorem 5: *Kenmotsu manifold M with $\widetilde{\nabla}^a$ and almost η -Ricci soliton (ζ, δ, μ, G) is an η^a -Einstein manifold.*

Replacing A and B by ζ in (4.5), gives

$$a^2(\delta + \mu) + 2(a^2 - 1) = 0, \text{ so } \delta + \mu = \frac{2(1-a^2)}{a^2}. \quad 4.6$$

Therefore,

Theorem 6: *A Kenmotsu manifold with almost η -Ricci soliton and $\widetilde{\nabla}^a$ is $(\zeta^a, \delta, \frac{2(1-a^2)}{a^2} - \delta, G^a)$.*

On a Kenmotsu manifold with Da-homothetic deformation and Schouten-van Kampen connection, equation (1.3) becomes,

$$\frac{1}{2}(\widetilde{L}_A G^a(A, B) = (\widetilde{scal}^a - \lambda)G^a(A, B)). \quad 4.7$$

Replacing A by ζ^a in (4.7), gives

$$\widetilde{scal}^a = \lambda.$$

Theorem 7: *A Kenmotsu manifold M with Yamabe soliton (ζ^a, λ, G^a) and $\widetilde{\nabla}^a$ is of constant scalar curvature.*

5. Example

Let $M = (A, B, C) \in \mathbb{R}^3 : C \neq 0$ with linearly independent vector fields at each point of M .

$$v_1 = v^C \frac{\partial}{\partial A}, v_2 = v^C \frac{\partial}{\partial B}, v_3 = \frac{\partial}{\partial C}. \quad 5.1$$

Define a Riemannian metric,

$$\begin{aligned} G_{ij} &= 1 \text{ for } i = j \\ &= 0 \text{ for } i \neq j. \end{aligned}$$

Define,

$$\eta(C) = G(C, v_3) \text{ with any } C \in \chi(M^3) \text{ \& } (1, 1) \text{ tensor field } J \text{ by,} \quad 5.2$$

$$Jv_1 = v_2, Jv_2 = -v_1, Jv_3 = 0. \quad 5.3$$

Hence by linearty property of J and G ,

$$\eta(v_3) = 1, J^2(C) = -z + \eta(C)\zeta. \quad 5.4$$

$$[v_1, v_3] = v_1, [v_2, v_3] = v_2, [v_1, v_2] = 0. \quad 5.5$$

$$D_{v_1} v_1 = -v_3, D_{v_2} v_2 = -v_3, D_{v_1} v_3 = v_1, D_{v_2} v_3 = v_2. \quad 5.6$$

Therefore $M^3(J, \zeta, \eta, G)$ is a Kenmotsu manifold with

$$K(v_1, v_2)v_2 = 2v_1, K(v_2, v_3)v_2 = -2v_3, K(v_1, v_3)v_3 = 2v_1. \quad 5.7$$

With (2.4), (2.5) is,

$$\tilde{\nabla}_A B = D_A B + \{G(A, B)\zeta - \eta(B)A\}. \quad 5.8$$

With (5.7) & (5.8) M is flat with $\tilde{\nabla}$.

By (3.1),

$$D_{v_1}^a v_1 = (a-2)v_3, D_{v_1}^a v_3 = v_1, D_{v_2}^a v_2 = (a-2)v_3, D_{v_2}^a v_3 = v_2. \quad 5.9$$

With (5.9), non-zero component of K^2 on M are

$$\begin{aligned} K^a(v_1, v_3)v_1 &= 2(a-2)v_3, K^a(v_1, v_3)v_3 = 2v_1, \\ K^a(v_2, v_3)v_2 &= 2(a-2)v_3, K^a(v_2, v_3)v_3 = 2v_2. \end{aligned} \quad 5.10$$

with (3.6) and (5.9),

$$\tilde{\nabla}_{v_1}^a v_3 = (a-1)v_1, \tilde{\nabla}_{v_2}^a v_3 = (a-1)v_2, \tilde{\nabla}_{v_2}^a v_2 = (a-1)v_3, \tilde{\nabla}_{v_1}^a v_1 = (a-1)v_3. \quad 5.11$$

Therefore with (5.11),

$$\tilde{K}^a(v_1, v_2)v_1 = 2(1-a)^2 v_2, \tilde{K}^a(v_1, v_2)v_2 = 2(1-a)^2 v_1. \quad 5.12$$

With (5.7), (5.10) and (5.12), the non zero components of Ricci tensor $\widetilde{\text{Ric}}$, $\widetilde{\text{Ric}}^a$ and $\widetilde{\text{Ric}}^a$ are

$$\text{Ric}(v_1, v_1) = 4, \text{Ric}(v_2, v_2) = 4, \text{Ric}(v_3, v_3) = 4. \quad 5.13$$

$$\widetilde{Ric}(v_1, v_1) = 8, \widetilde{Ric}(v_2, v_2) = 8, \widetilde{Ric}(v_3, v_3) = 6. \quad 5.14$$

$$Ric^a(v_1, v_1) = 8 - 4a, Ric^a(v_2, v_2) = 8 - 4a, Ric^a(v_3, v_3) = 4. \quad 5.15$$

$$\widetilde{Ric}^a(v_1, v_1) = a^2 - 6a + 4, \widetilde{Ric}^a(v_2, v_2) = a^2 - 6a + 4, \widetilde{Ric}^a(v_3, v_3) = 4(1 - a^2). \quad 5.16$$

For any $A, B \in \chi(M)$, write

$$A = a_1 v_1 + a_2 v_2 + a_3 v_3, B = b_1 v_1 + b_2 v_2 + b_3 v_3.$$

With (2.5) and (5.13) $\sim$ (5.16), gives

$$\begin{aligned} (\tilde{L}_{\zeta^a}^a G^a)(A, B) + 2\widetilde{Ric}^a(A, B) + 2\delta G^a(A, B) + 2\mu\eta^a(A)\eta^a(B) \\ = \{(a-1) + (a^2 - 6a + 4) - a\delta\}a_1b_1 \\ + \{(a-1) + (a^2 - 6a + 4) - a\delta\}a_2b_2 \\ + \{4(1 - a^2) - a^2(\delta + \mu)\}a_3b_3. \end{aligned}$$

$$\text{Hence } -2a^2 + 7a - 6 + a\delta = 0 \text{ and } 4(1 - a^2) - \frac{a^2}{2}(\delta + \mu) = 0.$$

$$\text{Therefore } \delta = 2a + \frac{7}{2} - \frac{6}{a} \text{ and } \mu = -2a + \frac{1}{2} + \frac{6}{a} - \frac{4}{a^2}$$

$$\text{so, } \delta + \mu = -\frac{4}{a^2} + 4.$$

$$\text{Therefore } M \text{ admits an } \eta\text{-Ricci soliton } \left(\left(\zeta, 2a + \frac{7}{2} - \frac{6}{a}, -2a + \frac{1}{2} + \frac{6}{a} - \frac{4}{a^2}, G^a \right) \right).$$

Hence the theorem 6 is verified.

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