

New open set on topological space with generalized topology

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Abstract

We all know the vast number of studies that presented several generalizations of open sets in topological spaces. On the other hand, since 2002 when A. Csaszar introduced the definition of generalized topology, other generalizations of open sets have appeared in generalized topological spaces. Our study provides a new generalization for an open set, where the definition will be a mixture of ordinary topology and generalized topology. Our new open set is named $X\omega$ -open set. We give several characterizations, properties, and examples related to the new concept.

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1. Introduction

A pair $(Z, \mathcal{X})$, where Z is a set and $\mathcal{X}$ is a family of subsets of Z , is denote a topological space. Members of $\mathcal{X}$ are said to be open in Z [1]. The complement of any open subset of Z is closed in Z [2]. We will denote the collection of all closed sets by $\mathcal{X}'$. If H is a subset of Z , the union of all open sets contained in H is called the interior of H and is symbolized by $int(H)$ whereas the intersection of all closed sets containing H is the closure of H and is symbolized by $cl(H)$ [3].

A generalized topological space is a pair $(Z, \mathcal{U})$, where Z is a set, and $\mathcal{U}$ is a collection of subsets of Z containing $\emptyset$ and closed under the arbitrary unions. Members of $\mathcal{U}$ are $\mathcal{U}$ -open sets. The complement of $\mathcal{U}$ -open is $\mathcal{U}$ -closed, and the collection of all $\mathcal{U}$ -closed sets is symbolized by $\mathcal{U}'$ [4]. $\mathcal{U}$ –

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the interior of H is the largest ω -open set in H and is symbolized by $int_{\omega}(H)$, while the smallest ω -closed set containing H is the ω -closure of H and is symbolized by $cl_{\omega}(H)$ [5]. The union of all elements of ω will be symbolized by M_{ω} , and (Z, ω) is said to be strong if $M_{\omega} = Z$ [6].

2. $X(\omega)$ – open set

Definition 2.1: Let (Z, X) be a topological space and let ω be a generalized topology on Z . A subset H of Z is said to be $X(\omega)$ – open set if there exists an ω – open set N such that $N \subseteq H \subseteq cl(N)$.

The collection of all $X(\omega)$ – open sets of Z will be denoted by $X(\omega)O(Z)$. The complement of $X(\omega)$ – open is $X(\omega)$ – closed set, the class of all $X(\omega)$ – closed sets in Z will be denoted by $X(\omega)C(Z)$.

Theorem 2.2: A subset H of a space (Z, X) with GT, ω is $X(\omega)$ – open if and only if $H \subseteq cl(int_{\omega}(H))$.

Proof:

The "if" part

Suppose that H is $X(\omega)$ – open set, then there exists an ω – open set N such that $N \subseteq H \subseteq cl(N)$, it follows that $int_{\omega}(N) \subseteq int_{\omega}(H)$, but $int_{\omega}(N) = N$ since N is ω – open, so $N \subseteq int_{\omega}(H)$, this means that $cl(N) \subseteq cl(int_{\omega}(H))$. Therefore, $H \subseteq cl(int_{\omega}(H))$.

The "only if" part

Suppose that $H \subseteq cl(int_{\omega}(H))$, put $N = int_{\omega}(H)$. It follows that $N \subseteq H \subseteq cl(N)$ where N is an ω – open. Hence H is $X(\omega)$ – open set.

Remark 2.3: Every ω – open (ω – closed) set is $X(\omega)$ – open ($X(\omega)$ – closed) set.

The inverse of Remark 2.3 is not validated, as shown in the example below.

Example 2.4: Let $Z = \{A, B, e\}$, $X = \{Z, \emptyset, \{A\}\}$, $X' = \{Z, \emptyset, \{B, e\}\}$, and let $\omega = \{\emptyset, \{A\}, \{e\}, \{A, e\}\}$, $\omega' = \{Z, \{B, e\}, \{A, B\}, \{B\}\}$, then $X(\omega)O(Z) = \{Z, \emptyset, \{A\}, \{e\}, \{A, e\}, \{B, e\}, \{A, B\}\}$ and $X(\omega)C(Z) = \{Z, \emptyset, \{A\}, \{e\}, \{B\}, \{B, e\}, \{A, B\}\}$. Not that, Z is $X(\omega)$ – open set, but not ω – open, and $\{A\}$ is $X(\omega)$ – closed, but not ω – closed.

Remark 2.5: Open set and $X(\omega)$ – open set are independent. As we show in the following example.

Example 2.6: Let $Z = \{\mathfrak{A}, \mathfrak{B}, \emptyset\}$, $\mathfrak{X} = \{Z, \emptyset, \{\mathfrak{A}\}\}$, $\mathfrak{X}' = \{Z, \emptyset, \{\mathfrak{B}, \emptyset\}\}$, and let $\omega = \{\emptyset, \{\emptyset\}, \{\mathfrak{A}, \emptyset\}\}$, $\omega' = \{Z, \{\mathfrak{A}, \mathfrak{B}\}, \{\mathfrak{B}\}\}$, then $\mathfrak{X}\omega O(Z) = \{Z, \emptyset, \{\emptyset\}, \{\mathfrak{A}, \emptyset\}, \{\mathfrak{B}, \emptyset\}\}$ and $\mathfrak{X}\omega C(Z) = \{Z, \emptyset, \{\mathfrak{A}\}, \{\mathfrak{B}\}, \{\mathfrak{A}, \mathfrak{B}\}\}$.

Not that, $\{\emptyset\}$ is $\mathfrak{X}\omega$ – open set, but not open, and $\{\mathfrak{A}\}$ is an open set, but not $\mathfrak{X}\omega$ – open.

Proposition 2.7: The union of any collection of $\mathfrak{X}\omega$ – open sets is $\mathfrak{X}\omega$ – open set.

Proof: Let $\{H_\alpha : \alpha \in \Lambda\}$ be a family of $\mathfrak{X}\omega$ – open sets, we have to show that $\bigcup_{\alpha \in \Lambda} H_\alpha$ is $\mathfrak{X}\omega$ – open set. From Theorem 2.2 we have $H_\alpha \subseteq cl\left(int_\omega(H_\alpha)\right)$ for each α , it follows that

$$\bigcup_{\alpha \in \Lambda} H_\alpha \subseteq \bigcup_{\alpha \in \Lambda} cl\left(int_\omega(H_\alpha)\right).$$

But $\bigcup_{\alpha \in \Lambda} cl\left(int_\omega(H_\alpha)\right) \subseteq cl\left(int_\omega\left(\bigcup_{\alpha \in \Lambda} H_\alpha\right)\right)$ by using properties of the closure of a set and properties of the ω – the interior of a set. Now we have $\bigcup_{\alpha \in \Lambda} H_\alpha \subseteq cl\left(int_\omega\left(\bigcup_{\alpha \in \Lambda} H_\alpha\right)\right)$. Hence $\bigcup_{\alpha \in \Lambda} H_\alpha$ is $\mathfrak{X}\omega$ – open set by Theorem 2.2.

Remark 2.8: The intersection of two $\mathfrak{X}\omega$ – open sets is not necessarily an $\mathfrak{X}\omega$ – open set. As we show in the following example.

Example 2.9: In Example 2.4, note that $\{a, b\}$ and $\{b, c\}$ are $\mathfrak{X}\omega$ – open sets, whereas $\{a, b\} \cap \{b, c\} = \{b\}$ is not $\mathfrak{X}\omega$ – open.

Theorem 2.10: For any topological space $(Z, \mathfrak{X})$ with GT, ω , $\mathfrak{X}\omega O(Z)$ is a generalized topology on Z .

Proof: Follows from Remark 2.3 and Proposition 2.7.

Remark 2.11: For any topological space $(Z, \mathfrak{X})$ with GT, ω , the union of all elements of $\mathfrak{X}\omega O(Z)$ will be denoted by $M_{\mathfrak{X}\omega}$, and $(Z, \mathfrak{X}\omega O(Z))$ is said to be strong if $M_{\mathfrak{X}\omega} = Z$.

Remark 2.11 In any topological space $(Z, \mathfrak{X})$ with GT, ω , $M_\omega \subseteq M_{\mathfrak{X}\omega}$, but not conversely.

For instance, see Example 2.6, $M_{\mathfrak{X}\omega} = Z$, while $M_\omega = \{a, c\}$.

Definition 2.12: Let $(Z, \mathfrak{X})$ be a topological space and let ω be a generalized topology on Z and let $\mathfrak{H}$ be a subset of Z . $\mathfrak{H}$ is an $\mathfrak{X}\omega$ – neighborhood of a point $z \in Z$ if there is an $\mathfrak{X}\omega$ – open subset G of Z such that $z \in G \subseteq \mathfrak{H}$. Every $\mathfrak{X}\omega$ –

open set containing z is also X_ω – a neighborhood of z , which is called X_ω – an open neighborhood.

Definition 2.13: Let (Z, X) be a topological space and let ω be a generalized topology on Z .

1. X_ω – the interior of a set H is symbolized by $int_{X_\omega}(H)$, and is defined by $int_{X_\omega}(H) = \bigcup \{G : G \text{ is } X_\omega \text{ – open}, G \subseteq H\}$.
2. X_ω – closure of a set H is symbolized by $cl_{X_\omega}(H)$, and is defined by $cl_{X_\omega}(H) = \bigcap \{F : F \text{ is } X_\omega \text{ – closed}, H \subseteq F\}$.

Example 2.14: Let's take Example 2.6, if $H = \{a, c\}$, then $int_{X_\omega}(H) = \{a, c\}$ and $cl_{X_\omega}(H) = Z$.

$$int_\omega(H) = \{a, c\} \text{ and } cl_\omega(H) = Z.$$

Theorem 2.15: Let (Z, X) be a topological space and let ω be a generalized topology on Z and let $H \subseteq Z$ and $z \in H$, then $z \in int_{X_\omega}(H)$ if and only if H is an X_ω – neighborhood of z .

Proof: $z \in int_{X_\omega}(H) = \bigcup \{G : G \text{ is } X_\omega \text{ – open}, G \subseteq H\} \Leftrightarrow \exists X_\omega \text{ – open subset } G \text{ of } Z \ni z \in G \subseteq H \Leftrightarrow H \text{ is an } X_\omega \text{ – neighborhood of } z$.

Theorem 2.16: Let (Z, X) be a topological space and let ω be a generalized topology on Z and let $H \subseteq Z$ and $z \in Z$, then $z \in cl_{X_\omega}(H)$ if and only if every X_ω – open neighborhood of z intersects H .

Proof:

The "if" part

Assume that $z \in cl_{X_\omega}(H) = \bigcap \{F : F \text{ is } X_\omega \text{ – closed}, H \subseteq F\}$ and suppose that there exists an X_ω – open neighborhood G of z such that $G \cap H = \emptyset$, it follows that $H \subseteq G^c$ which is X_ω – closed set with $z \notin G^c$, so $z \notin \bigcap \{F : F \text{ is } X_\omega \text{ – closed}, H \subseteq F\}$ which is a contradiction.

The "only if" part

Assume that every X_ω – open neighborhood of z intersects H and suppose that $z \notin cl_{X_\omega}(H) = \bigcap \{F : F \text{ is } X_\omega \text{ – closed}, H \subseteq F\}$, then there exists an X_ω – closed subset F of Z with $H \subseteq F$ such that $z \notin F$, so $z \in F^c$ which is X_ω – open, but $F^c \cap H = \emptyset$, that implies to contradiction.

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