

ON INEXTENSIBLE FLOWS OF CURVES ACCORDING TO ALTERNATIVE MOVING FRAME

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ABSTRACT. In this paper, we investigate inextensible flows of curves according to alternative moving frame in Euclidean space $\mathbb{E}^3$. Using the Frenet frame of the given curve, we present partial differential equations. The concepts with the inextensible flows are analyzed by using alternative moving frame.

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1. INTRODUCTION

Flows of particles is an important active research field in the differential geometry studies and it is heavily studied for a long time and it is still under consideration. Also, it introduces the miniature, architect, simulation of kinematic motion or design of highways and mechanic tools. Uzunoğlu et. al. have discussed a new frame called it as a alternative moving frame, [17].

The flow of a curve is said to be inextensible if the arclength is preserved. Physically, inextensible curve flows give rise to motions in which no strain energy is induced. The swinging motion of a cord of fixed length, for example can be described by inextensible curve flows. Such motions arise quite naturally in a wide range of physical applications. There are many approaches to the elastica. For

example, Körpinar have constructed a new method for inextensible flows of time-like curves in a conformally flat, quasi conformally flat and conformally symmetric 4-dimensional LPSasakian manifold. With this new representation it has been derived the necessary and sufficient condition for the given curve to be the inextensible flow. By using curvature tensor field, he gave some characterizations for curvatures of a timelike curve in a conformally flat, quasi conformally flat and conformally symmetric 4-dimensional LP-Sasakian manifold, [8].

On the other hand, The study of flow theory has received considerable attention in mathematical physics. For example, Körpinar et al have have been extensively discussed time-evolution equations that the intrinsic quantities of curves to construct binormal spherical curves as surfaces in terms of inextensible flows in E^3 . They gave necessary and sufficient condition for a binormal spherical curves as surfaces to be a Bonnet surface, [9].

In this paper, we investigate inextensible flows of curves according to alternative moving frame in Euclidean space E^3 . Using the Frenet frame of the given curve, we present partial differential equations. The concepts with the inextensible flows are analyzed by using alternative moving frame.

2. PRELIMINARIES

Let $\alpha : I \rightarrow E^3$ be an arbitrary curve in E^3 . Recall that the curve α is said a unit speed curve (or parameterized by arclength functions) if $\langle \alpha'(s), \alpha'(s) \rangle = 1$, where $\langle, \rangle$ denotes the standard inner product of R^3 given by

$$\langle, \rangle = dx_1^2 + dx_2^2 + dx_3^2,$$

where (x_1, x_2, x_3) is a rectangular coordinate system of E^3 . In particular, the norm of an arbitrary vector $a \in R^n$ is given by $\|a\|^2 = \langle a, a \rangle$.

In Euclidean 3-space, we know that each unit speed curve has at least four continuous derivatives, one can associate three orthogonal unit vector fields $\mathbf{T}, \mathbf{N}, \mathbf{B}$ are the tangent, the principal normal and the binormal vector fields, respectively.

Firstly, assume that $\{\mathbf{T}, \mathbf{N}, \mathbf{B}\}$ be the Frenet frame field along α . Then, the Frenet frame satisfies the following Frenet-Serret equations:

$$\begin{aligned}\mathbf{T}'(s) &= \kappa(s)\mathbf{N}(s), \\ \mathbf{N}'(s) &= -\kappa(s)\mathbf{T}(s) + \tau(s)\mathbf{B}(s), \\ \mathbf{B}'(s) &= -\tau(s)\mathbf{N}(s),\end{aligned}\tag{2.1}$$

where κ is the curvature of α and τ its torsion.

Secondly, denote by $\{\mathbf{N}, \mathbf{C}, \mathbf{N} \times \mathbf{C} = \mathbf{W}\}$ the alternative moving frame along the curve α in Euclidean 3-space. Putting

$$\mathbf{N}, \mathbf{C} = \frac{\mathbf{N}'}{\|\mathbf{N}'\|}, \mathbf{W} = \frac{\tau\mathbf{T} + \kappa\mathbf{B}}{\sqrt{\kappa^2 + \tau^2}}$$

are the unit principal normal vector, the derivative of principal normal vector and the Darboux vector, respectively. For the derivatives of the alternative moving frame, we have

$$\begin{aligned}\mathbf{N}'(s) &= f(s)\mathbf{C}(s), \\ \mathbf{C}'(s) &= -f(s)\mathbf{N}(s) + g(s)\mathbf{W}(s), \\ \mathbf{W}'(s) &= -g(s)\mathbf{C}(s),\end{aligned}\tag{2.1}$$

where $f = \kappa\sqrt{1 + H^2}$ and $g = \sigma f$ are curvatures of the curve α in terms of alternative moving frame, [17].

3. INEXTENSIBLE FLOWS ACCORDING TO ALTERNATIVE MOVING FRAME

Let $\alpha(u, t)$ is a one parameter family of smooth curves in $\mathbb{E}^3$.

Any flow of α can be represented according to alternative moving frame as

$$(3.1) \quad \frac{\partial \alpha}{\partial t} = \beta_1 \mathbf{N} + \beta_2 \mathbf{C} + \beta_3 \mathbf{W},$$

where $\beta_1, \beta_2, \beta_3 \in C^\infty(\mathbb{E}^3)$.

Letting the arclength variation be

$$s(u, t) = \int_0^u v du.$$

Also, inextensible flow of curve can be expressed by the condition

$$\frac{\partial}{\partial t} s(u, t) = \int_0^u \frac{\partial v}{\partial t} du = 0.$$

Definition 3.1. The flow $\frac{\partial \alpha}{\partial t}$ in $\mathbb{E}^3$ are said to be inextensible if

$$\frac{\partial}{\partial t} \left| \frac{\partial \alpha}{\partial u} \right| = 0.$$

Lemma 3.2. Let $\frac{\partial \alpha}{\partial t}$ be a smooth flow of the curve α according to the alternative moving frame. The flow is inextensible if and only if

$$(3.2) \quad \frac{\partial v}{\partial t} = \frac{\tau}{\varpi} \left(\frac{\partial \beta_3}{\partial u} + \beta_2 g v \right) - \frac{\kappa}{\varpi} \left(\frac{\partial \beta_2}{\partial u} + \beta_1 f v - \beta_3 g v \right)$$

where $\varpi = \sqrt{\kappa^2 + \tau^2}$ and $\beta_1, \beta_2, \beta_3 \in C^\infty(\mathbb{E}^3)$.

Proof. By using Definition 3.1, we obtain

$$\frac{\partial}{\partial u} \frac{\partial \alpha}{\partial t} = \left(\frac{\partial \beta_1}{\partial u} - \beta_2 f v \right) \mathbf{N} + \left(\frac{\partial \beta_2}{\partial u} + \beta_1 f v - \beta_3 g v \right) \mathbf{C} + \left(\frac{\partial \beta_3}{\partial u} + \beta_2 g v \right) \mathbf{W}.$$

From the alternative moving frame, we have

$$\begin{aligned} \mathbf{B} &= \frac{\kappa}{\varpi} \mathbf{W} + \frac{\tau}{\varpi} \mathbf{C}, \\ \mathbf{T} &= \frac{\tau}{\varpi} \mathbf{W} - \frac{\kappa}{\varpi} \mathbf{C}, \end{aligned}$$

where $\varpi = \sqrt{\kappa^2 + \tau^2}$.

Suppose that $\frac{\partial \alpha}{\partial t}$ be a smooth flow of the curve α . Using definition of α , we have

$$\frac{\partial v}{\partial t} = \frac{\tau}{\varpi} \mathbf{W} - \frac{\kappa}{\varpi} \mathbf{C}, \left(\frac{\partial \beta_1}{\partial u} - \beta_2 f v \right) \mathbf{N} + \left(\frac{\partial \beta_2}{\partial u} + \beta_1 f v - \beta_3 g v \right) \mathbf{C} + \left(\frac{\partial \beta_3}{\partial u} + \beta_2 g v \right) \mathbf{W} >.$$

Therefore, by using (3.1), an algebraic calculus gives that

$$\frac{\partial v}{\partial t} = \frac{\tau}{\varpi} \left(\frac{\partial \beta_3}{\partial u} + \beta_2 g v \right) - \frac{\kappa}{\varpi} \left(\frac{\partial \beta_2}{\partial u} + \beta_1 f v - \beta_3 g v \right)$$

Making necessary calculations from above equation, we have (3.2), which proves the lemma.

Lemma 3.3. Let $\frac{\partial \alpha}{\partial t}$ be a smooth flow of the curve α according to the alternative moving frame. The flow is inextensible if and only if

$$(3.3) \quad \tau \left(\frac{\partial \beta_3}{\partial u} + \beta_2 g v \right) = \kappa \left(\frac{\partial \beta_2}{\partial u} + \beta_1 f v - \beta_3 g v \right),$$

where $\beta_1, \beta_2, \beta_3 \in C^\infty(\mathbb{E}^3)$.

Proof. Using lemma 3.2, we easily have (3.3).

Theorem 3.4. Let $\frac{\partial \alpha}{\partial t}$ be a smooth inextensible flow of the curve α according to alternative moving frame. Then, the flow of $\mathbf{N}$ is given by

$$\begin{aligned} \frac{\partial \mathbf{N}}{\partial t} &= \frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) - \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) f - \frac{\partial \kappa}{\partial t} \right] \mathbf{N} \\ &+ \frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) + \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \right] \mathbf{C} \\ &+ \frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) + \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) g \right] \mathbf{W}. \end{aligned}$$

Theorem 3.5. Let $\frac{\partial \alpha}{\partial t}$ be a smooth inextensible flow of the curve α according to alternative moving frame. Then, the flow of $\mathbf{C}$ is given by

$$\begin{aligned} \frac{\partial \mathbf{C}}{\partial t} &= \frac{1}{f} \left[\frac{\partial}{\partial s} \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) - \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) f - \frac{\partial \kappa}{\partial t} \right] \right. \right. \\ &- f \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) + \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \right] \right] \mathbf{N} \\ &+ \frac{1}{f} \left[-\frac{\partial f}{\partial t} + \frac{\partial}{\partial s} \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) + \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \right] \right. \right. \\ &+ \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) - \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) f - \frac{\partial \kappa}{\partial t} \right] f - \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) \right. \right. \right. \\ &+ \left. \left. \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) g \right] g \right] \mathbf{C} + \frac{1}{f} \left[\frac{\partial}{\partial s} \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) + \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) g \right] \right. \right. \\ &+ \left. \left. \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) + \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \right] g \right] \right] \mathbf{W}. \end{aligned}$$

Theorem 3.6. Let $\frac{\partial \alpha}{\partial t}$ be a smooth inextensible flow of the curve α according to alternative moving frame. Then, the flow of $\mathbf{W}$ is given by

$$\begin{aligned} \frac{\partial \mathbf{W}}{\partial t} &= \frac{\varpi}{\tau} \left[\left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) + \frac{1}{f} \frac{\kappa}{\varpi} \left[\frac{\partial}{\partial s} \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) - \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) f \right. \right. \right. \right. \right. \\ &- \left. \left. \frac{\partial \kappa}{\partial t} \right] \right] - f \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) + \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \right] \right] \mathbf{N} \\ &+ \frac{\varpi}{\tau} \left[\left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) + \frac{1}{f} \frac{\kappa}{\varpi} \left[-\frac{\partial f}{\partial t} + \frac{\partial}{\partial s} \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) \right. \right. \right. \right. \right. \\ &+ \left. \left. \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \right] \right] + \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) - \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) f \right. \right. \right. \\ &- \left. \left. \frac{\partial \kappa}{\partial t} \right] \right] f - \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) + \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) g \right] g \right] + \frac{\partial}{\partial t} \left[\frac{\kappa}{\varpi} \right] \mathbf{C} \\ &+ \frac{\varpi}{\tau} \left[\left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) + \frac{1}{f} \frac{\kappa}{\varpi} \left[\frac{\partial}{\partial s} \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) + \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) g \right] \right. \right. \right. \right. \\ &+ \left. \left. \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) + \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \right] g \right] \right] - \frac{\partial}{\partial t} \left[\frac{\tau}{\varpi} \right] \right] \mathbf{W}. \end{aligned}$$

$$\begin{aligned}
& + [\frac{\partial}{\partial s} [\frac{1}{f} [\frac{\partial}{\partial s} [\frac{1}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_3}{\partial s} + \beta_2 g) + (\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g) g]] + [\frac{1}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_2}{\partial s} \\
& + \beta_1 f - \beta_3 g) + (\frac{\partial \beta_1}{\partial s} - \beta_2 f) f - (\frac{\partial \beta_3}{\partial s} + \beta_2 g) g]] g]] + g [\frac{1}{f} [-\frac{\partial f}{\partial t} + \frac{\partial}{\partial s} [\frac{1}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_2}{\partial s} \\
& + \beta_1 f - \beta_3 g) + (\frac{\partial \beta_1}{\partial s} - \beta_2 f) f - (\frac{\partial \beta_3}{\partial s} + \beta_2 g) g]] + [\frac{1}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_1}{\partial s} - \beta_2 f) - (\frac{\partial \beta_2}{\partial s} \\
& + \beta_1 f - \beta_3 g) f - \frac{\partial \kappa}{\partial t}]] f - [\frac{1}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_3}{\partial s} + \beta_2 g) + (\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g) g]] g]]] \mathbf{W}.
\end{aligned}$$

Then using the following equality:

$$\frac{\partial}{\partial t} \frac{\partial}{\partial s} \mathbf{C} = -\frac{\partial f}{\partial t} \mathbf{N} + \frac{\partial g}{\partial t} \mathbf{W} - f \frac{\partial}{\partial t} \mathbf{N} + g \frac{\partial}{\partial t} \mathbf{W}$$

we have

$$\begin{aligned}
\frac{\partial}{\partial t} \frac{\partial}{\partial s} \mathbf{C} &= [-\frac{\partial f}{\partial t} + \frac{g\varpi}{\tau} [(\frac{\partial \beta_1}{\partial s} - \beta_2 f) + \frac{1}{f} \frac{\kappa}{\varpi} [\frac{\partial}{\partial s} [\frac{1}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_1}{\partial s} - \beta_2 f) - (\frac{\partial \beta_2}{\partial s} \\
& + \beta_1 f - \beta_3 g) f - \frac{\partial \kappa}{\partial t}]] - f [\frac{1}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g) + (\frac{\partial \beta_1}{\partial s} - \beta_2 f) f - (\frac{\partial \beta_3}{\partial s} \\
& + \beta_2 g) g]]]] - \frac{f}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_1}{\partial s} - \beta_2 f) - (\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g) f - \frac{\partial \kappa}{\partial t}]] \mathbf{N} + [\frac{g\varpi}{\tau} [(\frac{\partial \beta_2}{\partial s} \\
& + \beta_1 f - \beta_3 g) + \frac{1}{f} \frac{\kappa}{\varpi} [-\frac{\partial f}{\partial t} + \frac{\partial}{\partial s} [\frac{1}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g) + (\frac{\partial \beta_1}{\partial s} - \beta_2 f) f \\
& - (\frac{\partial \beta_3}{\partial s} + \beta_2 g) g]] + [\frac{1}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_1}{\partial s} - \beta_2 f) - (\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g) f - \frac{\partial \kappa}{\partial t}]] f \\
& - [\frac{1}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_3}{\partial s} + \beta_2 g) \\
& + (\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g) g]] g] + \frac{\partial}{\partial t} [\frac{\kappa}{\varpi}]] - \frac{f}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g) + (\frac{\partial \beta_1}{\partial s} - \beta_2 f) f - (\frac{\partial \beta_3}{\partial s} \\
& - \beta_2 f) f - (\frac{\partial \beta_3}{\partial s} + \beta_2 g) g]] \mathbf{C} + [\frac{\partial g}{\partial t} + \frac{g\varpi}{\tau} [(\frac{\partial \beta_3}{\partial s} + \beta_2 g) \\
& + \frac{1}{f} \frac{\kappa}{\varpi} [\frac{\partial}{\partial s} [\frac{1}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_3}{\partial s} + \beta_2 g) \\
& + (\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g) g]] + [\frac{1}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g) + (\frac{\partial \beta_1}{\partial s} - \beta_2 f) f - (\frac{\partial \beta_3}{\partial s} \\
& + \beta_2 g) g]] g] - \frac{\partial}{\partial t} [\frac{\tau}{\varpi}]] - \frac{f}{\kappa} [\frac{\partial}{\partial s} (\frac{\partial \beta_3}{\partial s} + \beta_2 g) + (\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g) g]] \mathbf{W}.
\end{aligned}$$

By using above mixed differentiation and coefficient of $\mathbf{N}$, we have corollary. This completes the proof.

On the other hand, differentiating $\frac{\partial \mathbf{W}}{\partial s}$ with respect to t , gives

Since

This completes the proof. $\square$

Corollary 3.11.

$$\begin{aligned}
& \left[\frac{\partial}{\partial s} \left[\frac{\varpi}{\tau} \left[\left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) + \frac{1}{f} \frac{\kappa}{\varpi} \left[-\frac{\partial f}{\partial t} + \frac{\partial}{\partial s} \left[\frac{1}{\kappa} \left[\frac{\partial \beta_2}{\partial s} \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) \right. \right. \right. \right. \right. \right. \right. \right. \right. \right. \\
& + \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \left] \right] + \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) - \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) f - \frac{\partial \beta_2}{\partial t} \right] \right] \\
& - \beta_3 g \left] f - \frac{\partial \kappa}{\partial t} \right] \left] f - \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) + \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) g \right] \right] g \right] + \frac{\partial}{\partial t} \left[\frac{\kappa}{\varpi} \right] \left] \right] \\
& + f \left[\frac{\varpi}{\tau} \left[\left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) + \frac{1}{f} \frac{\kappa}{\varpi} \left[\frac{\partial}{\partial s} \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) - \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) f - \frac{\partial \kappa}{\partial t} \right] \right] \right. \right. \right. \right. \right. \\
& - f \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) + \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \right] \right] \left] \right] - g \left[\frac{\varpi}{\tau} \left[\left(\frac{\partial \beta_3}{\partial s} \right. \right. \right. \\
& + \beta_2 g \right) + \frac{1}{f} \frac{\kappa}{\varpi} \left[\frac{\partial}{\partial s} \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) + \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) g \right] \right] + \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_2}{\partial s} \right. \right. \right. \\
& + \beta_1 f - \beta_3 g \right) + \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \left] \right] g \right] - \frac{\partial}{\partial t} \left[\frac{\tau}{\varpi} \right] \left] \left] \right] \\
= & \left[-\frac{\partial g}{\partial t} - \frac{g}{f} \left[-\frac{\partial f}{\partial t} + \frac{\partial}{\partial s} \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) \right. \right. \right. \right. \right. \right. \\
& + \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \left] \right] \\
& + \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) - \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) f - \frac{\partial \kappa}{\partial t} \right] \right] f - \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) \right. \right. \\
& + \left. \left. \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) g \right] \right] g \left] \right].
\end{aligned}$$

Proof. It is obvious by using Theorem 3.10.

Corollary 3.12.

$$\begin{aligned}
& \left[\frac{\partial}{\partial s} \left[\frac{\varpi}{\tau} \left[\left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) + \frac{1}{f} \frac{\kappa}{\varpi} \left[\frac{\partial}{\partial s} \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) + \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) g \right] \right. \right. \right. \right. \right. \right. \\
& + \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) + \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \right] g \right] - \frac{\partial}{\partial t} \left[\frac{\tau}{\varpi} \right] \right] \\
& + g \left[\frac{\varpi}{\tau} \left[\left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) + \frac{1}{f} \frac{\kappa}{\varpi} \left[-\frac{\partial f}{\partial t} + \frac{\partial}{\partial s} \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) + \left(\frac{\partial \beta_1}{\partial s} \right. \right. \right. \right. \right. \right. \right. \right. \\
& - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \right] + \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) - \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) f - \frac{\partial \kappa}{\partial t} \right] \right] f \\
& - \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) + \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) g \right] g \right] + \frac{\partial}{\partial t} \left[\frac{\kappa}{\varpi} \right] \right] \\
& = -\frac{g}{f} \left[\frac{\partial}{\partial s} \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) + \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) g \right] + \left[\frac{1}{\kappa} \left[\frac{\partial}{\partial s} \left(\frac{\partial \beta_2}{\partial s} + \beta_1 f - \beta_3 g \right) \right. \right. \right. \right. \right. \right. \\
& + \left(\frac{\partial \beta_1}{\partial s} - \beta_2 f \right) f - \left(\frac{\partial \beta_3}{\partial s} + \beta_2 g \right) g \right] g \right].
\end{aligned}$$

Proof. It is obvious by using Theorem 3.10.

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